

# PARTICLE CLUSTERING IN PERIODICALLY FORCED PLANETARY RINGS

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# BACKGROUND AND GOAL

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- Analytic models of rings predict a variety of structure, but the models are limited.
  - $N$ -body simulations have their own assumptions, but allow one to calculate many parameters and view structure that develops given those assumptions and parameters.
  - Esposito *et al.* (2012) predicted with an analytic model that structure in the rings follows a predator-prey situation between mass aggregates and mean-square velocity.
- ~ We want to test that model with  $N$ -body simulations.
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# METHOD (IDEALIZED FORCING)

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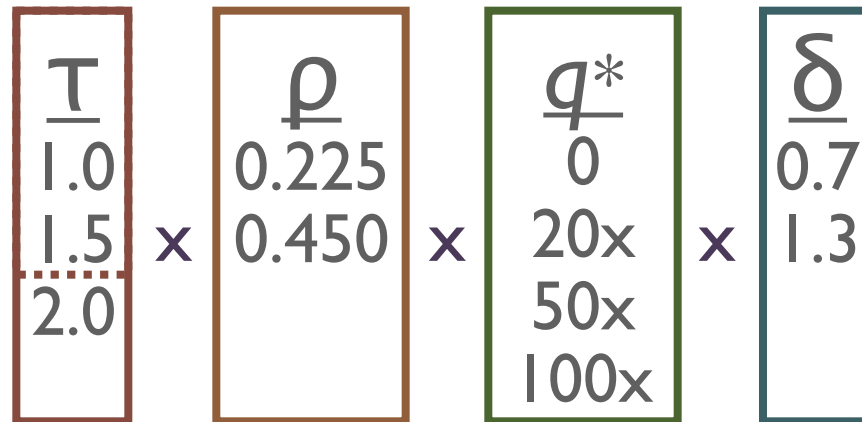
- REBOUND *N*-body code. (Rein & Liu, 2011)
- \*Adjusted integrator to add forcing to  $a_x$ :  $\dot{+} = q \cdot \sin(\delta \cdot t) \cdot \sin(2\pi x/L_x)$ 
  - $q$  sets the magnitude of the forcing
  - $\delta$  sets the forcing so it is not at resonance with the orbital period
  - second  $\sin()$  sets forcing at 0 at cell boundaries to simplify ghost cells
- Calculate every 1/40<sup>th</sup> orbit: Viscosity, mean-squared velocity, mass aggregates.
- Esposito *et al.* (2012) observed predator-prey behavior after 4 forced orbits; we ran 6.

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\*Does **not** track azimuthal forcing. **Does** conserve angular momentum.

# PARAMETER SPACE

- Location: Outer edge B ring,  $a_0 = 117.56$  Mm
- $L_x = L_y = 10 \cdot \lambda_{\text{crit}}$  (cell sizes 340 – 1360 m)
- $N = 37,000 - 1,169,000$  (largest haven't finished yet;  $N = 493,000$  have)
- **Four** simulations run for every parameter set: 192 simulations,  $\approx 15,300$  CPU hours (1.74 yrs). (Robbins *et al.* (2010) used 27,000 CPU hrs)



\*Multiples of the RMS particle acceleration at steady-state (orbit 6.000).  $q = 0$  is unforced.

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# MASS AGGREGATES

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- First variable is mean-square velocity.
- Second variable is mean aggregate mass (second moment of mass distribution):

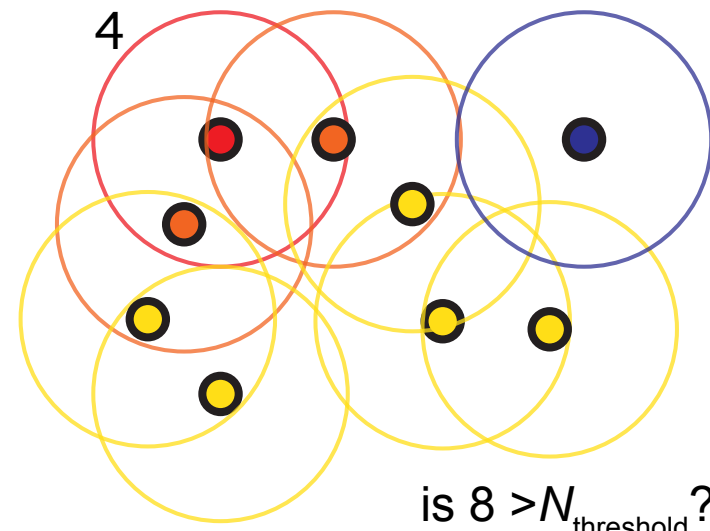
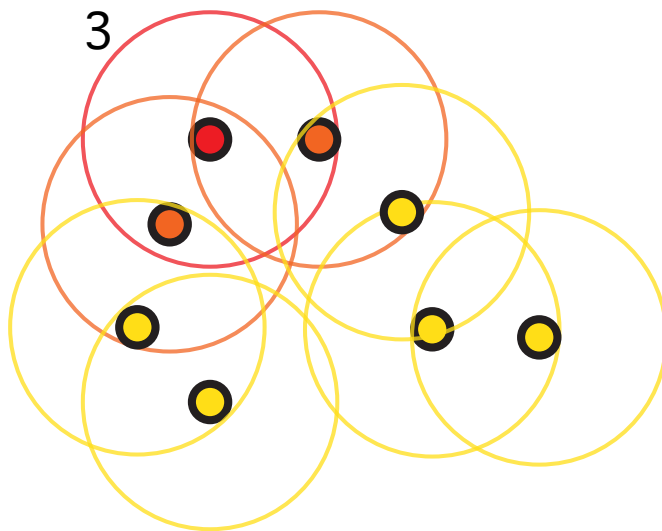
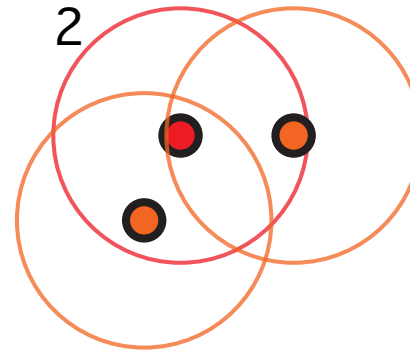
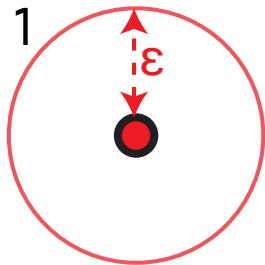
$$\mathcal{M} = \frac{\sum_j \left( \sum_i m_i \right)^2}{\sum_j \left( \sum_i m_i \right)}$$

- But: Need a method to identify clumps.
    - needs to be a quantitative method
    - needs to be a hard cluster code (particles uniquely belong to one cluster)
    - needs to have a minimum number of adjustable parameters
    - already have a DBSCAN (Ester *et al.*, 1996) implementation for craters (Robbins *et al.*, 2014), adapted to use for rings particles!
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# MASS AGGREGATES: HOW DBSCAN WORKS (2 INPUTS)

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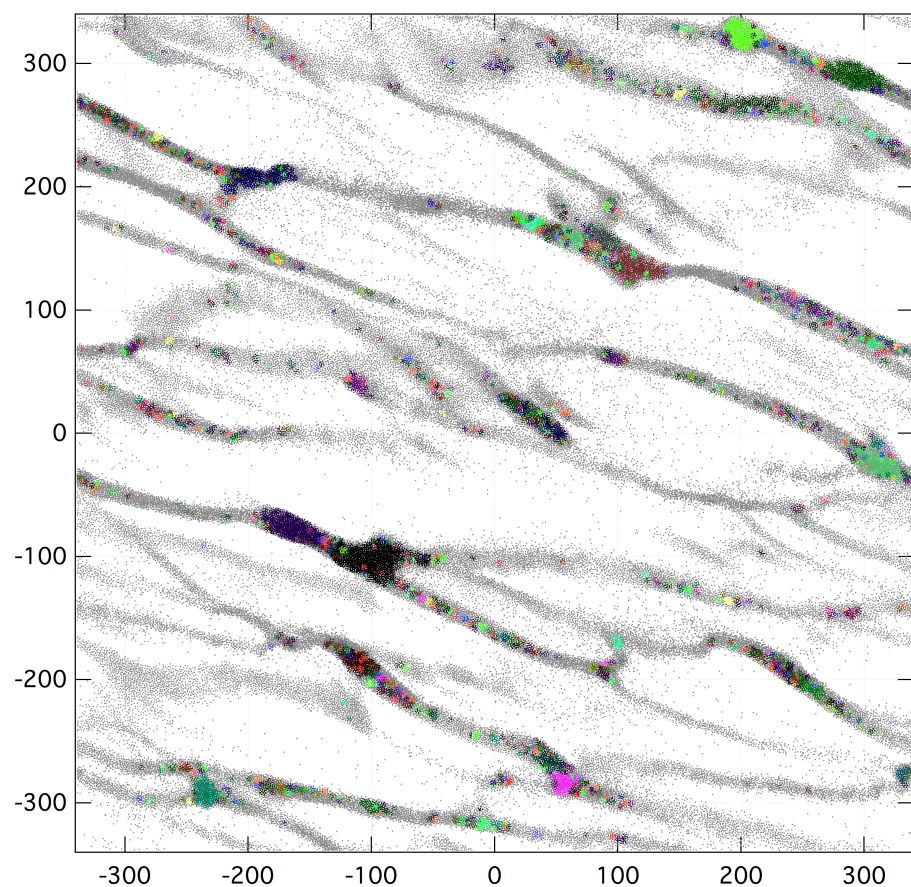
is  $8 > N_{\text{threshold}}$  ?

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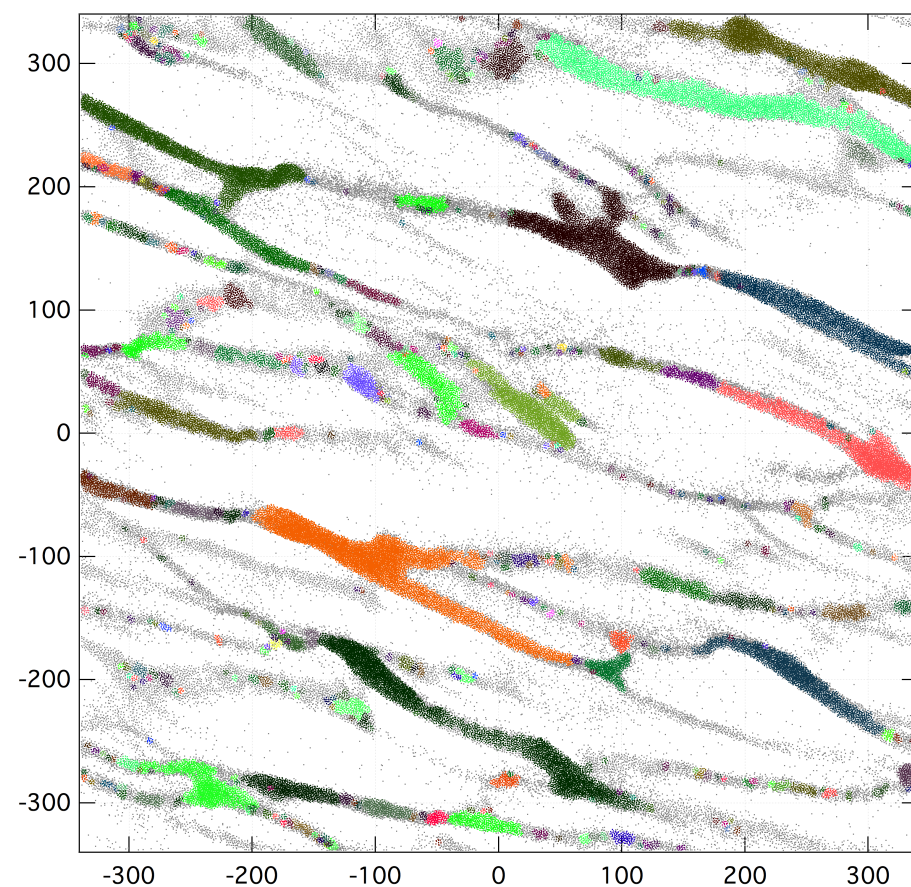
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# MASS AGGREGATES: EXAMPLES ( $\tau=1.0$ , $\rho=0.45$ )

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$R = 2.2r_p$  ||  $N = 10$



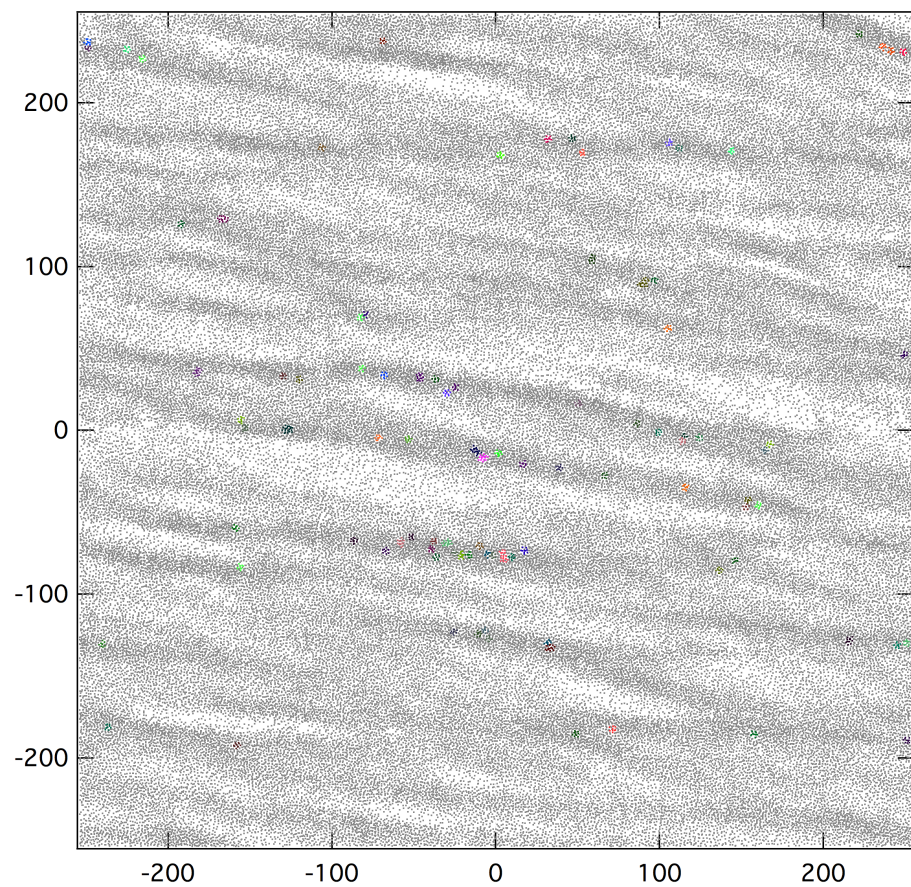
$R = 2.7r_p$  ||  $N = 12$

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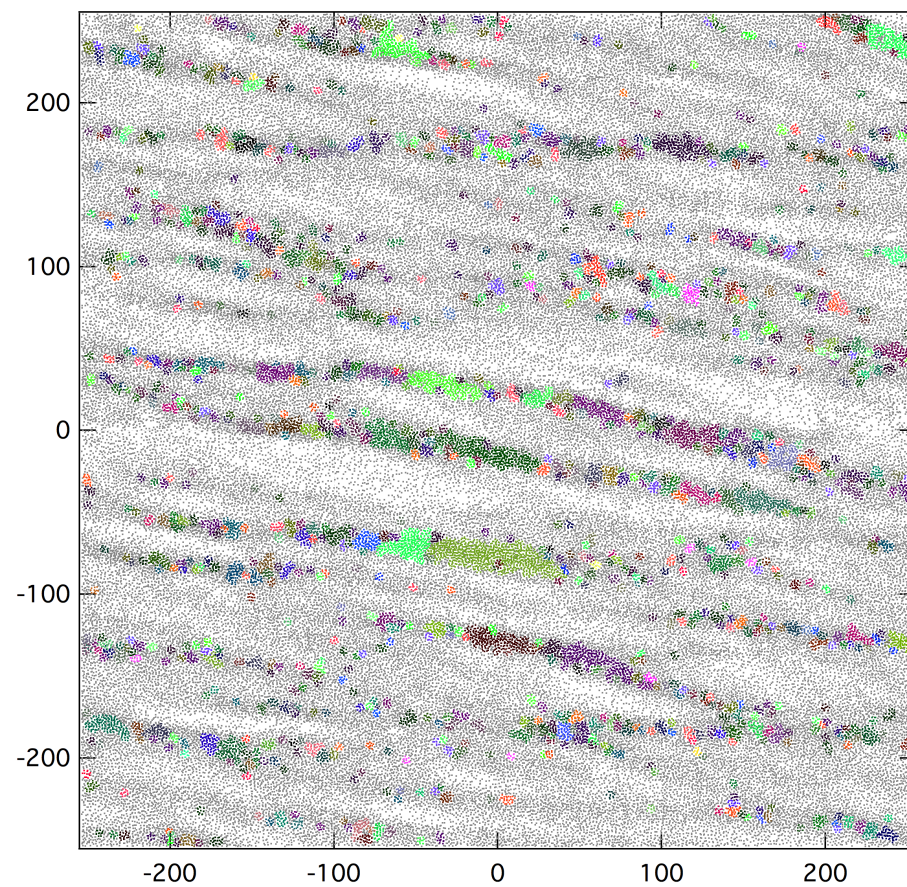
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# MASS AGGREGATES: EXAMPLES ( $\tau=1.5$ , $\rho=0.225$ )

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$R = 2.2r_p$  ||  $N = 10$



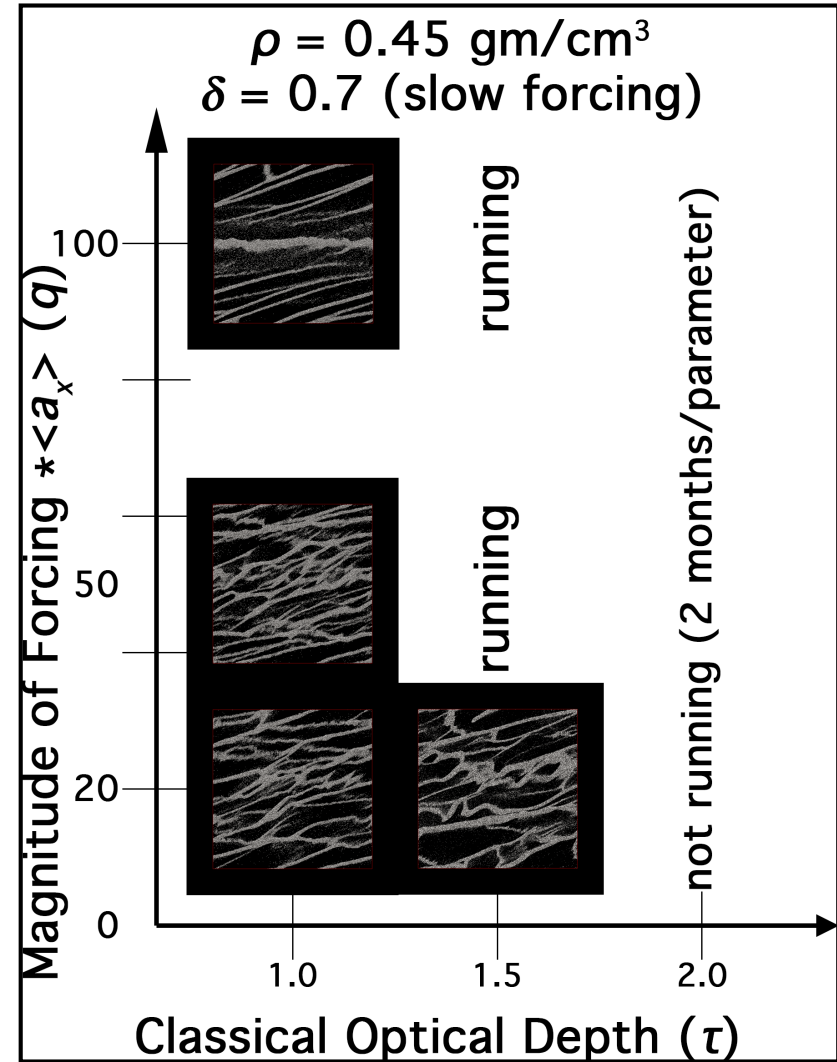
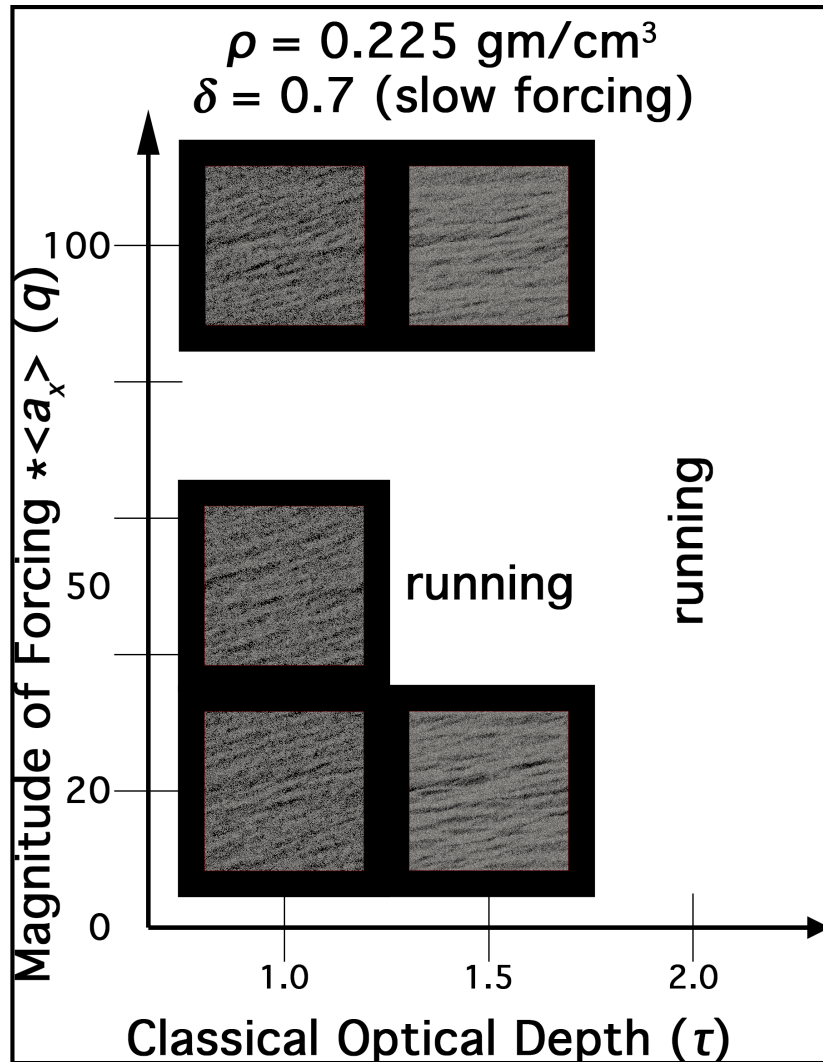
$R = 2.7r_p$  ||  $N = 12$

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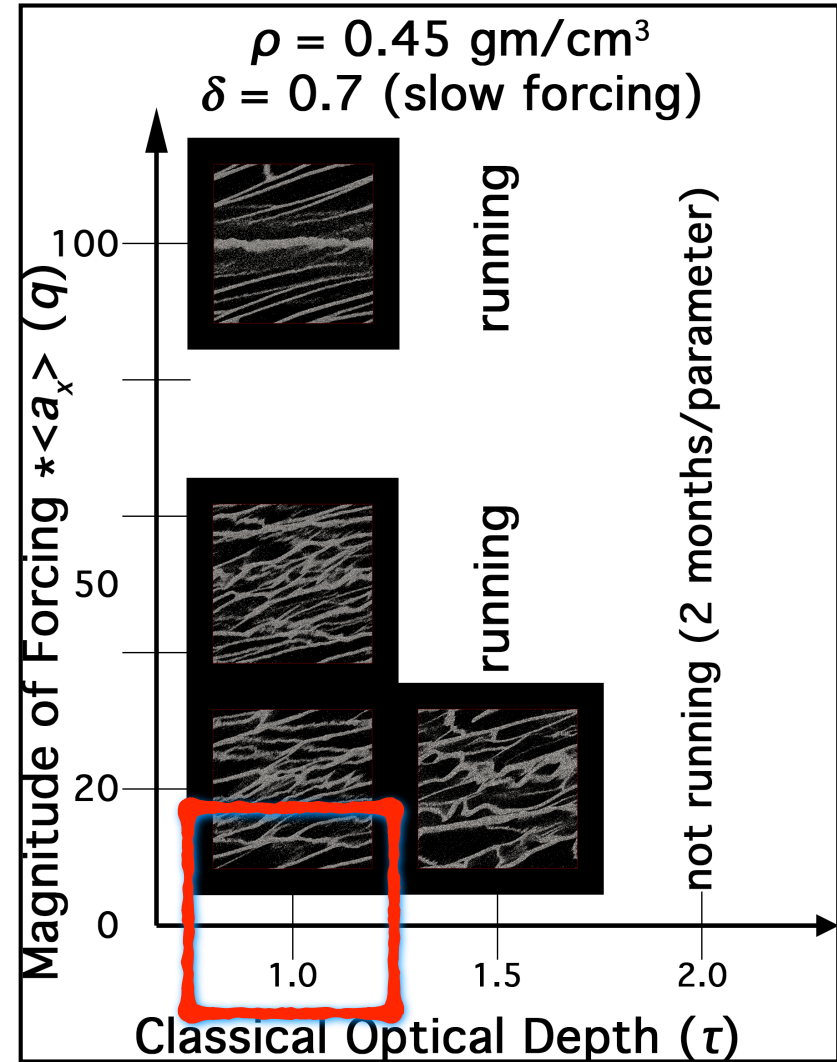
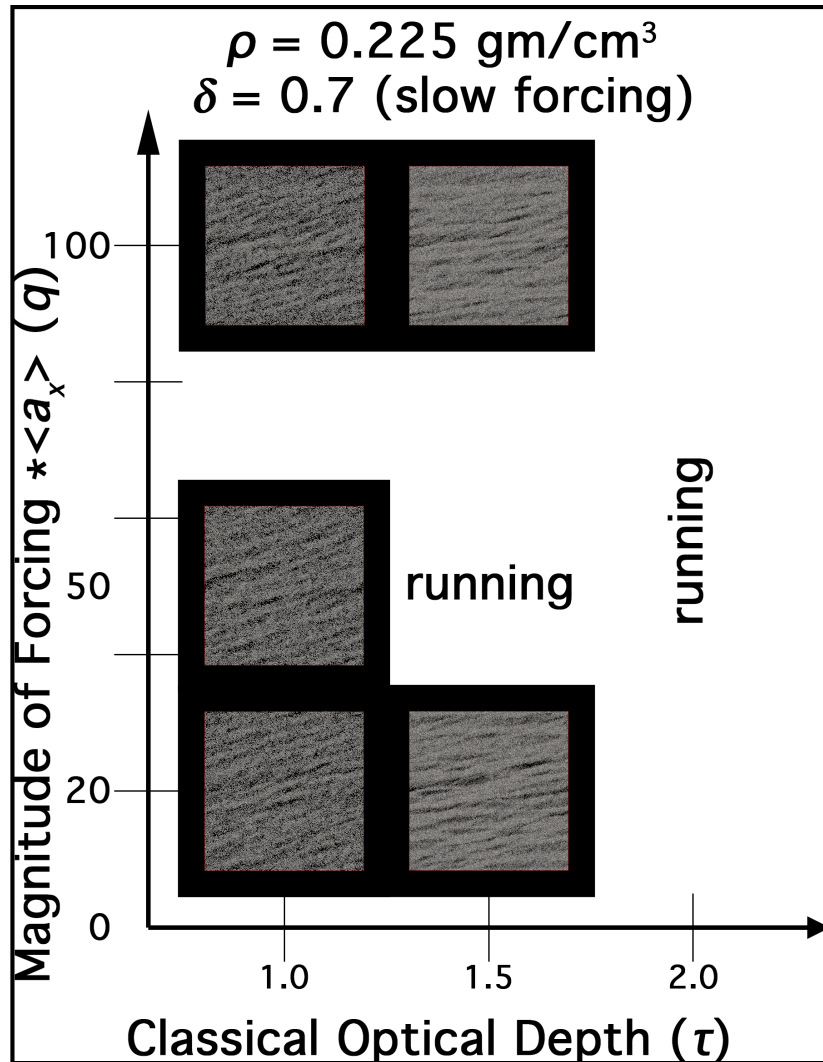
RESULTS:

# PARAMETER SPACE NAVIGATION



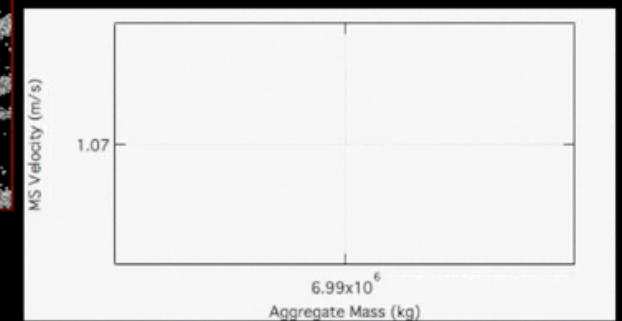
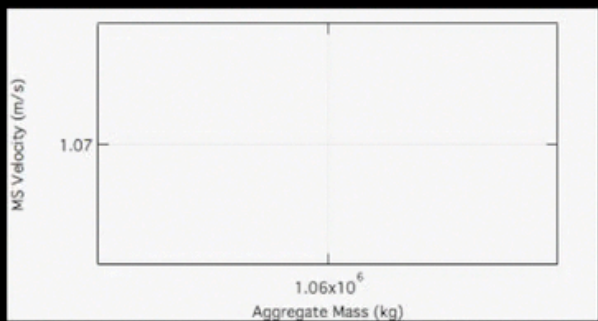
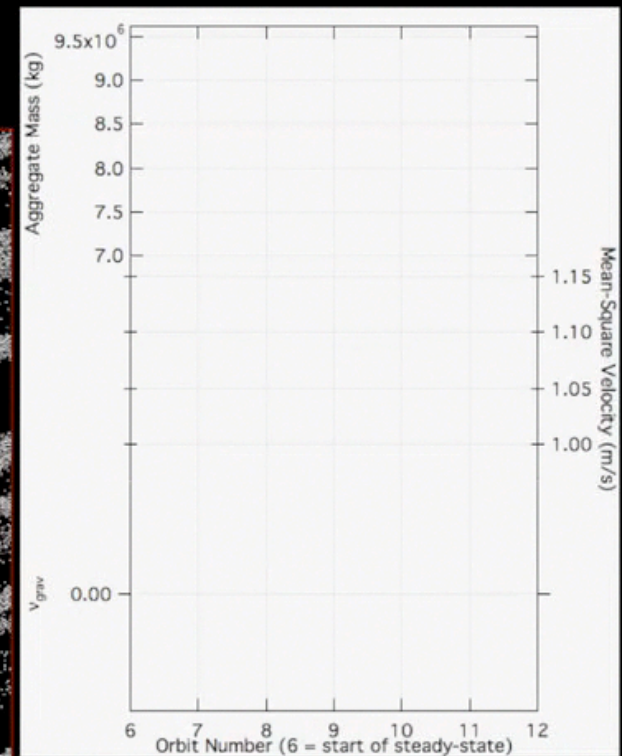
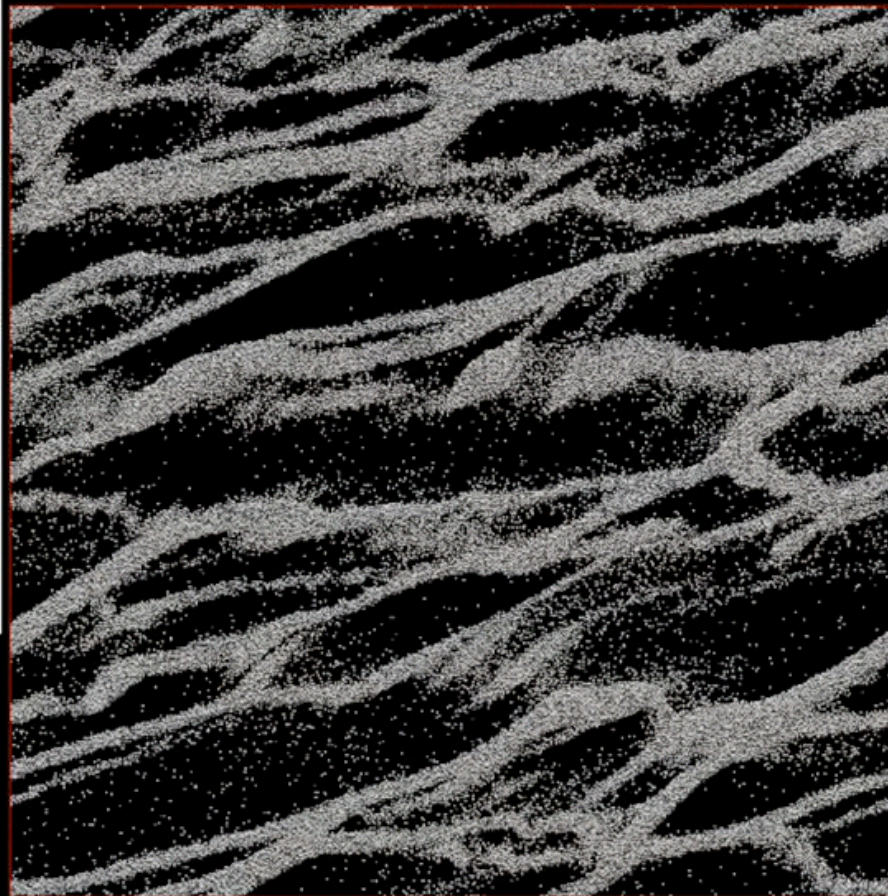
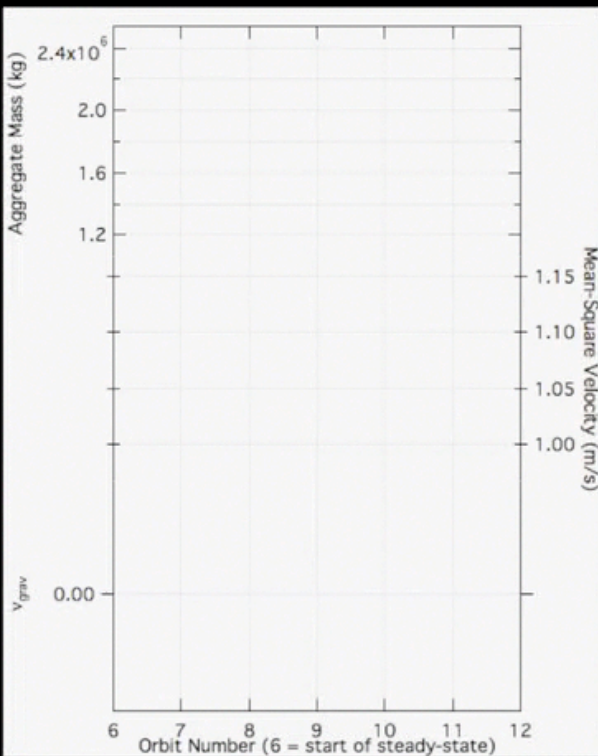
RESULTS:

# PARAMETER SPACE NAVIGATION



RESULTS:

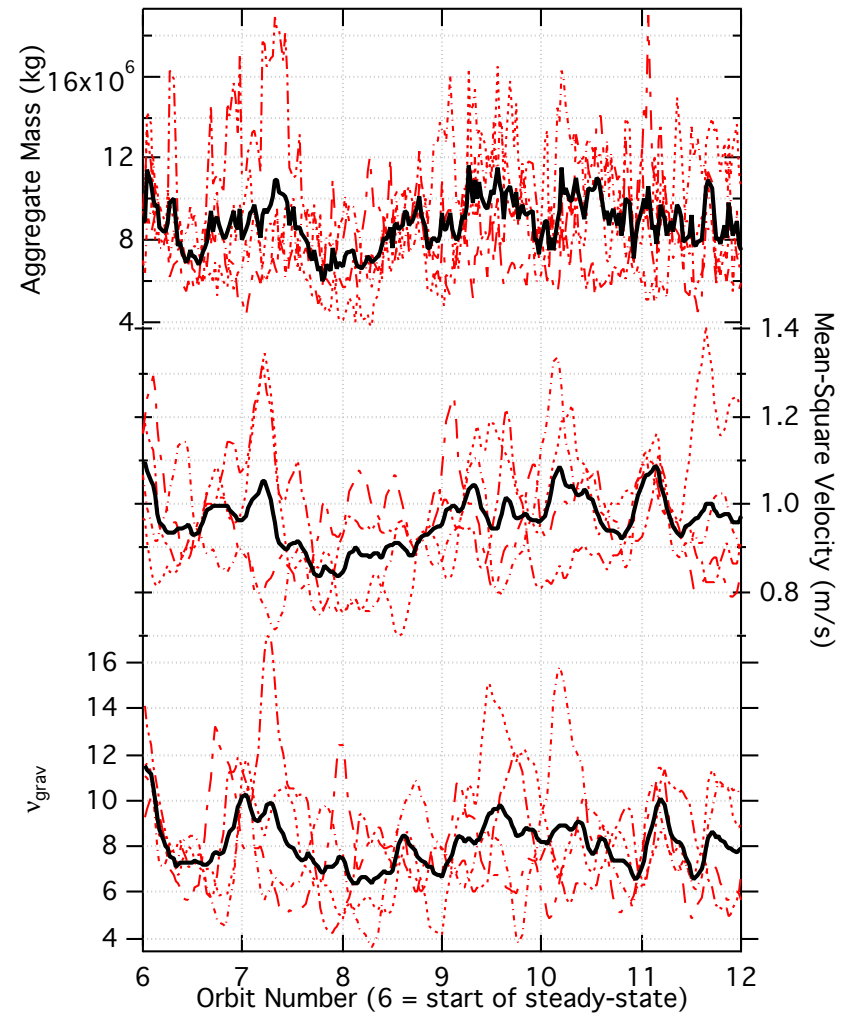
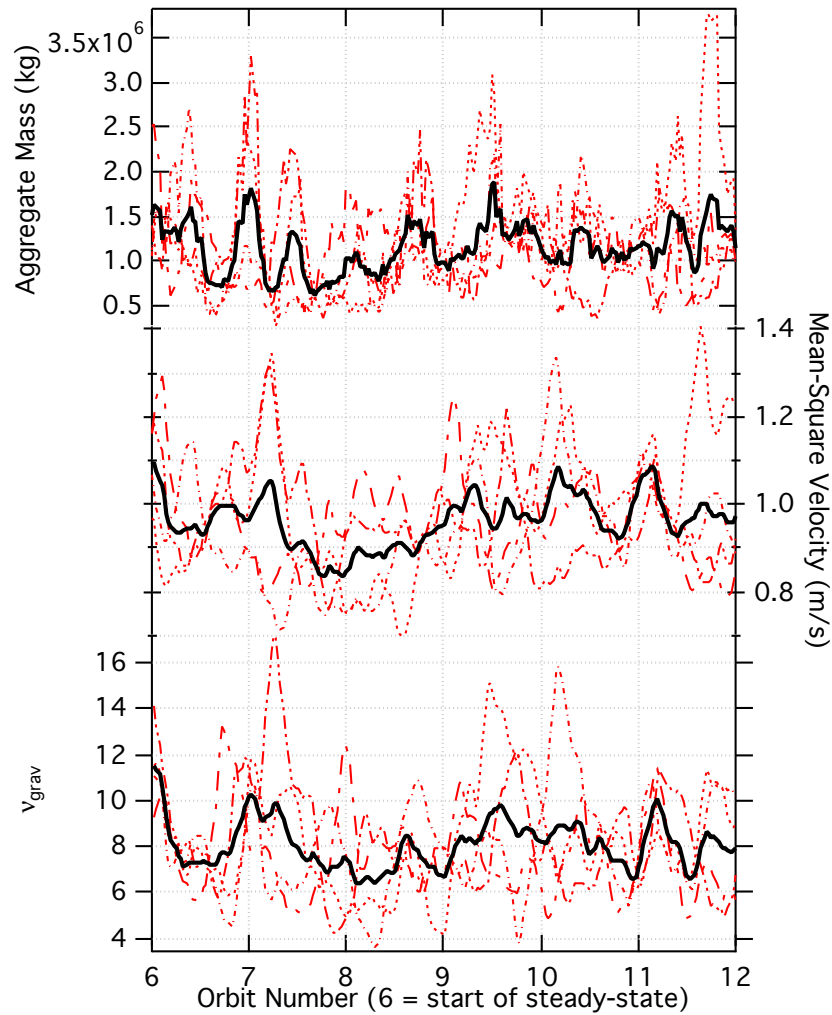
$\tau = 1.0$ ,  $\rho = 0.45$ , UNFORCED (STILL SEE VARIABILITY)



RESULTS:

$\tau = 1.0$ ,  $\rho = 0.45$ , UNFORCED (STILL SEE VARIABILITY)

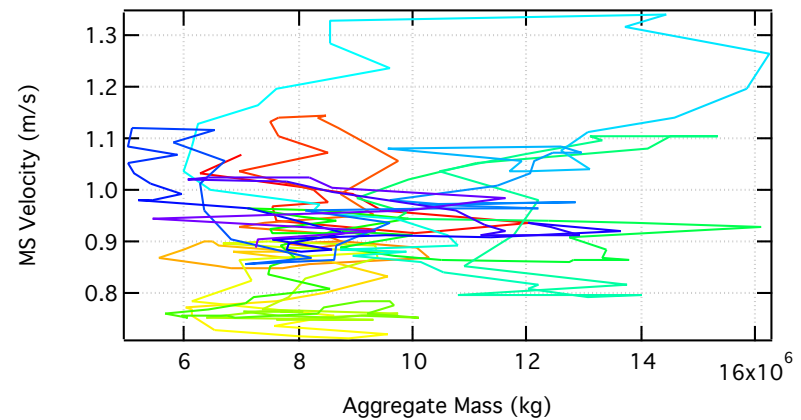
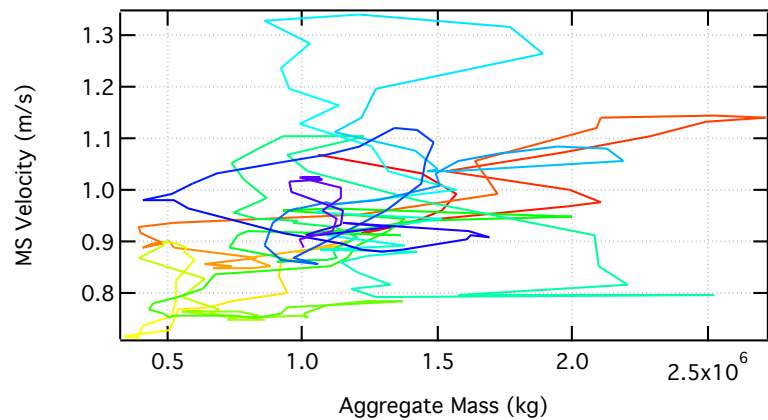
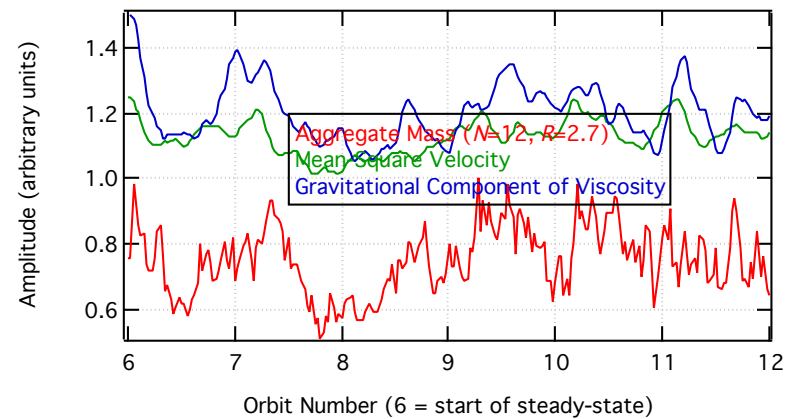
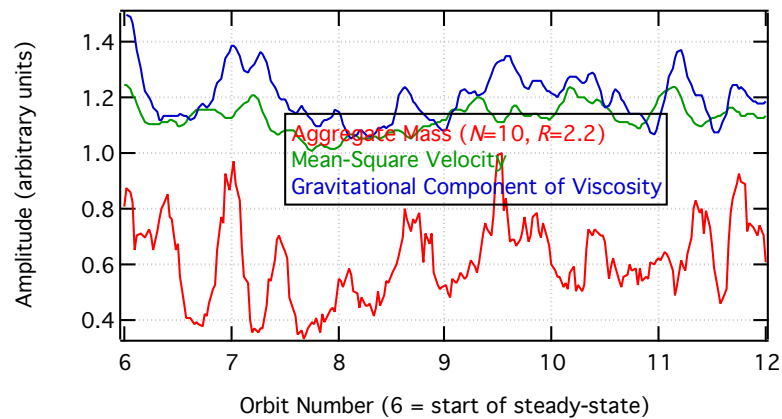
Unforced



RESULTS:

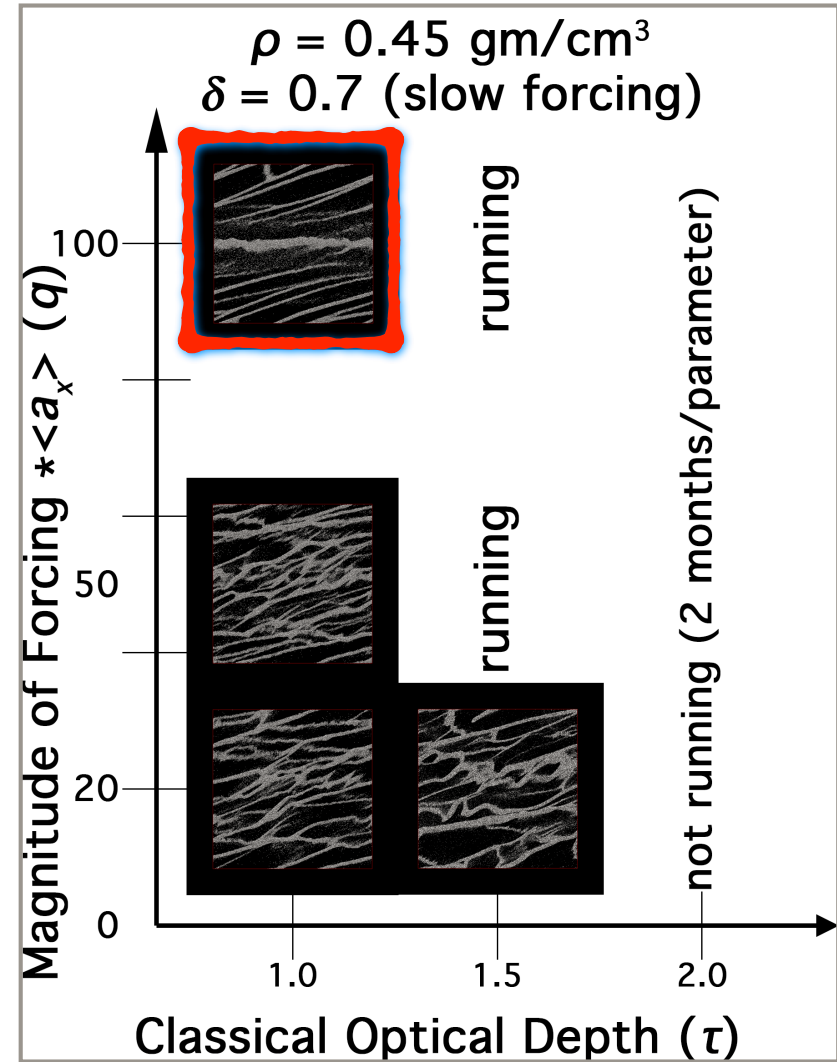
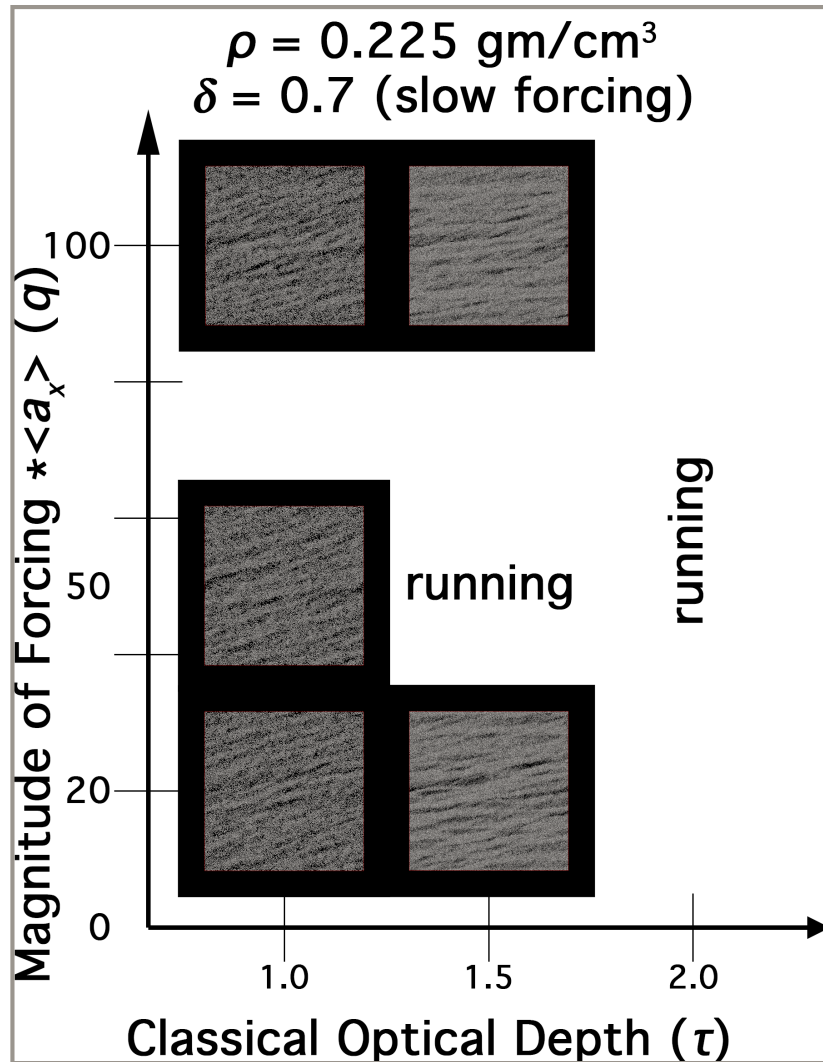
$\tau = 1.0$ ,  $\rho = 0.45$ , UNFORCED (STILL SEE VARIABILITY)

Unforced



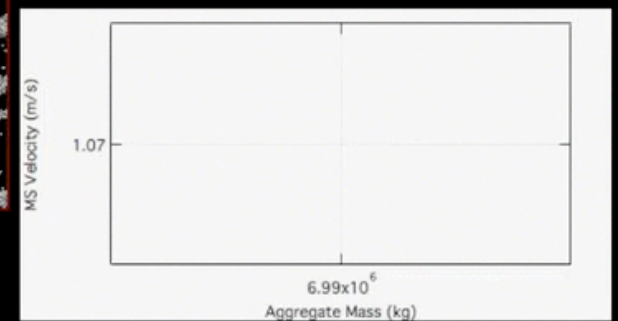
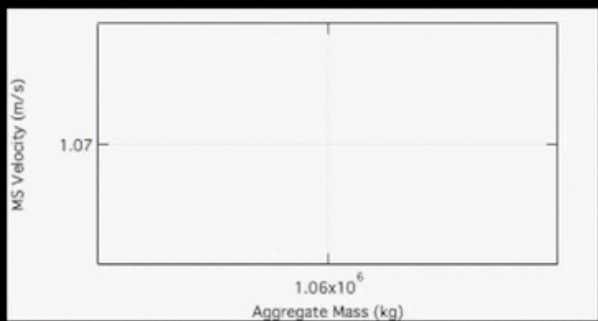
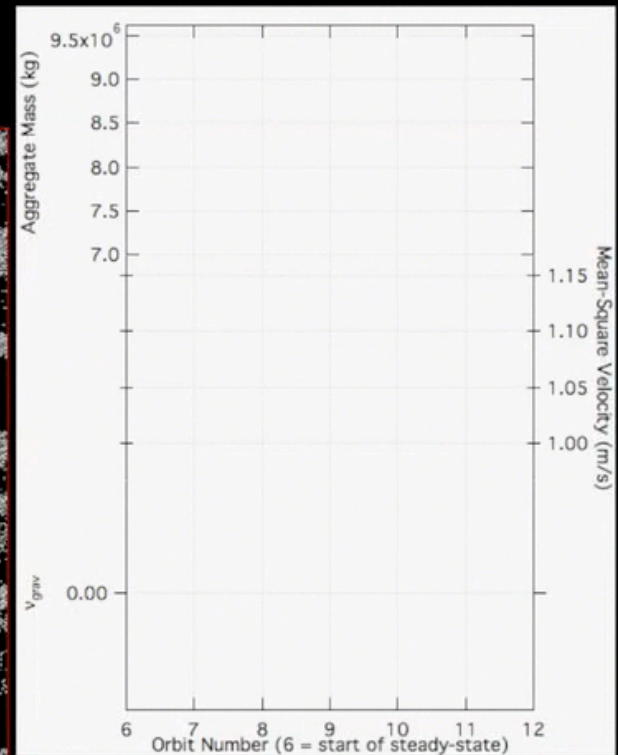
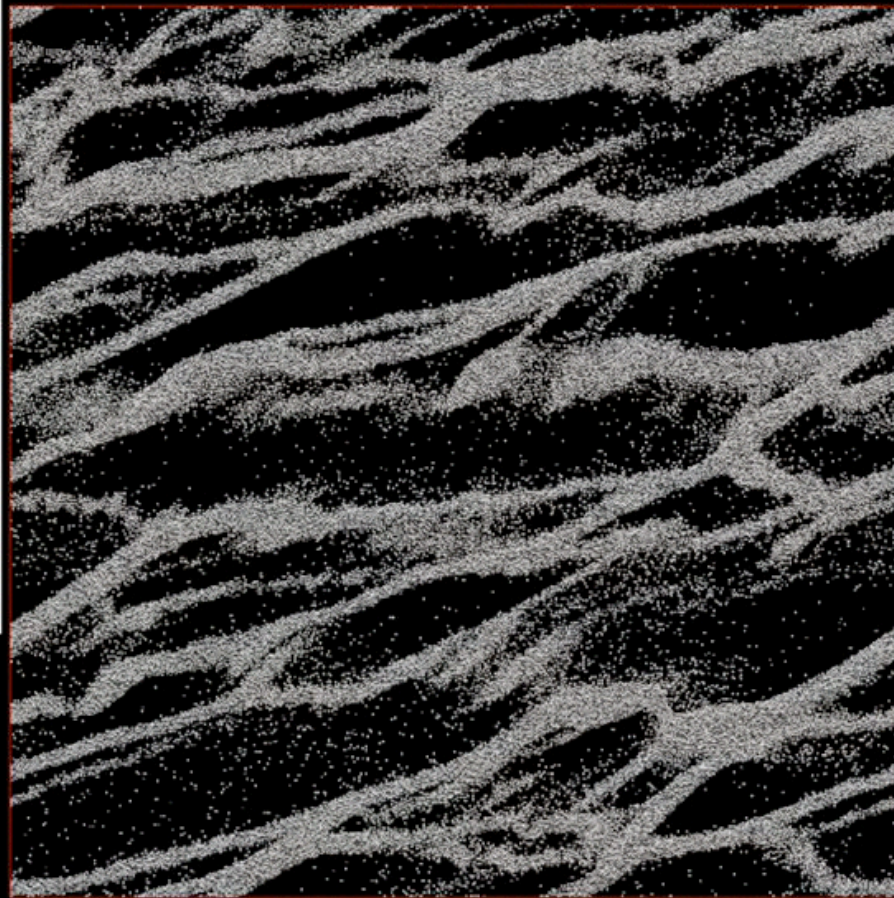
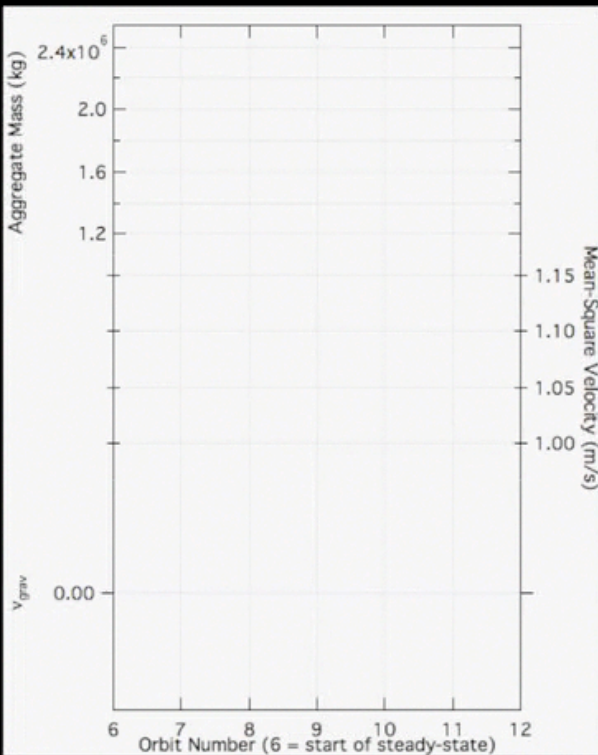
RESULTS:

# NAVIGATIONAL CHART



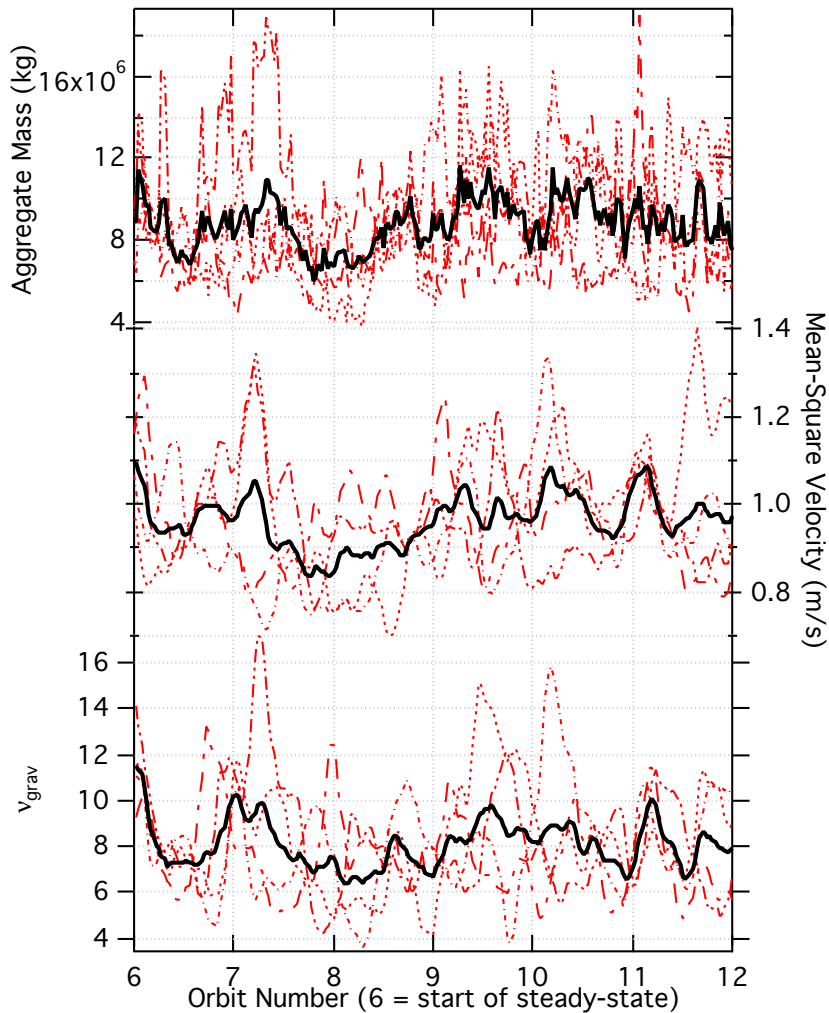
RESULTS (SIMILAR BEHAVIOR TO LEWIS & STEWART ENKE GAP SIMULATIONS):

$$\tau = 1.0, \rho = 0.45, q = 100\times, \delta = 0.7$$

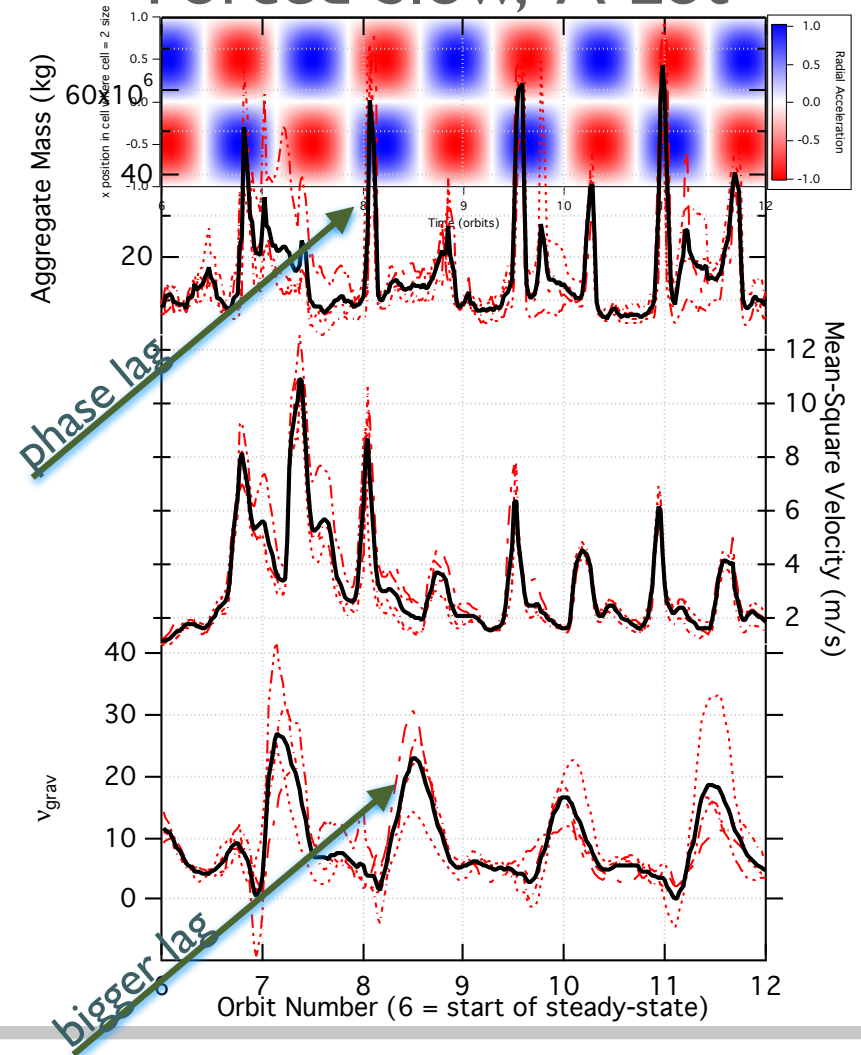


# RESULTS (CLUSTER CODE "CLUMPS" PARAMETERS): $\tau=1.0$ , $\rho=0.45$ , $q=100\times$ , $\delta=0.7$

## Unforced



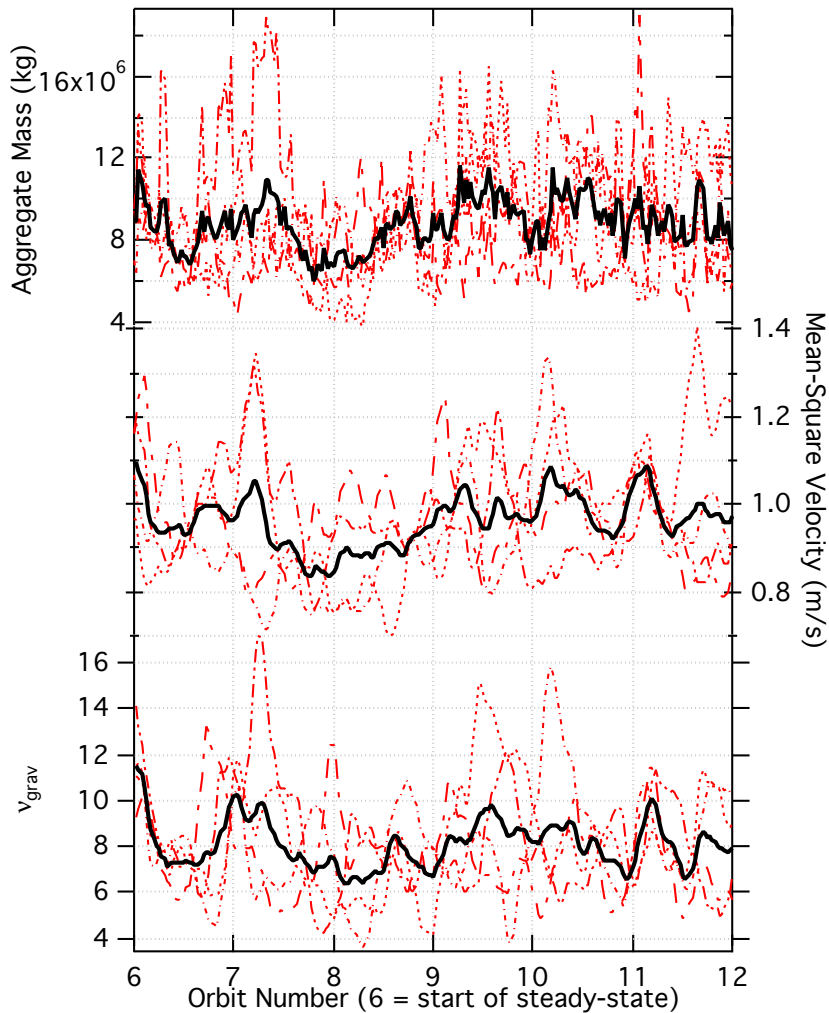
## Forced Slow, A Lot



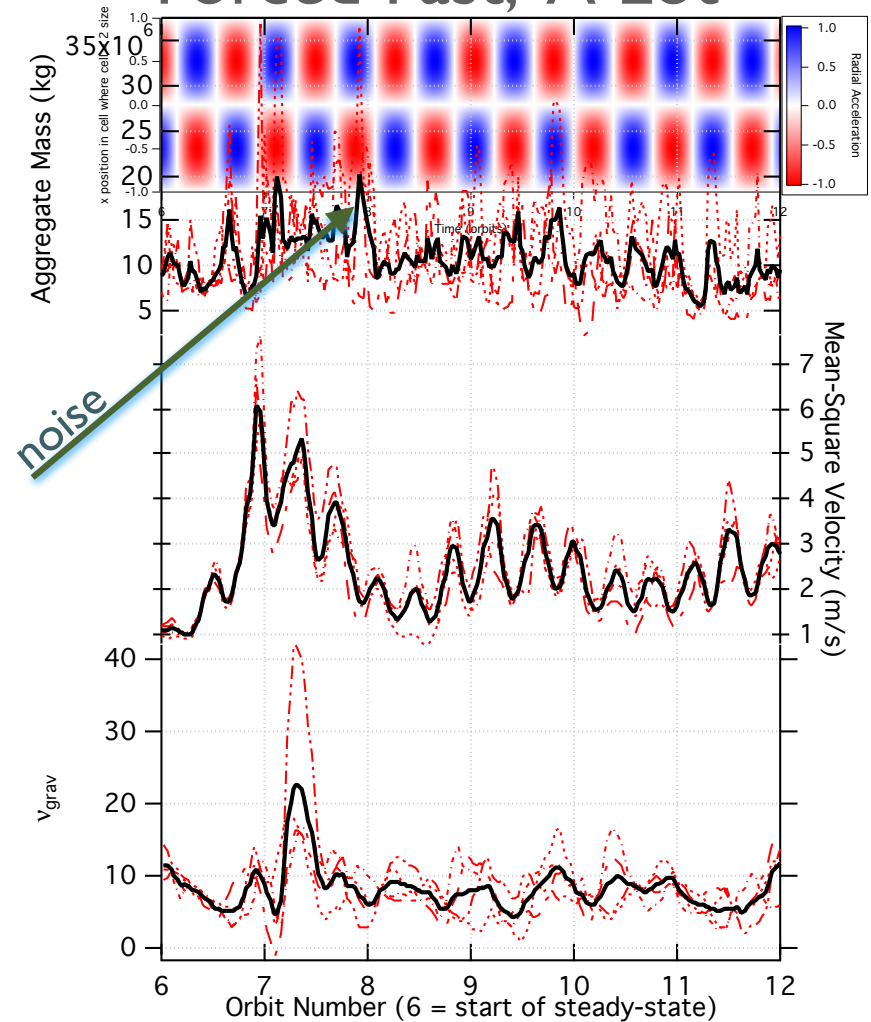


# RESULTS (CLUSTER CODE "CLUMPS" PARAMETERS): $\tau = 1.0$ , $\rho = 0.45$ , $q = 100\times$ , $\delta = 1.3$

## Unforced



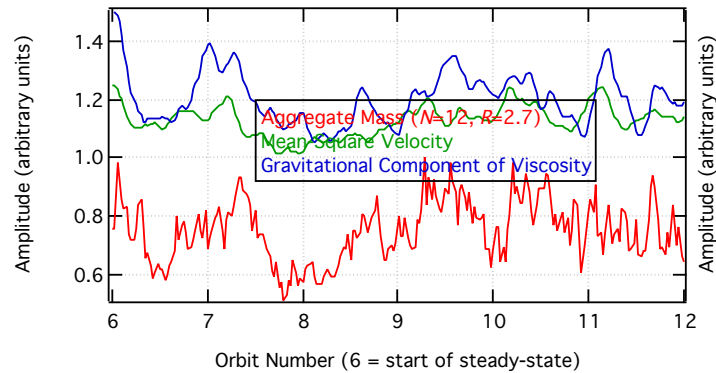
## Forced Fast, A Lot



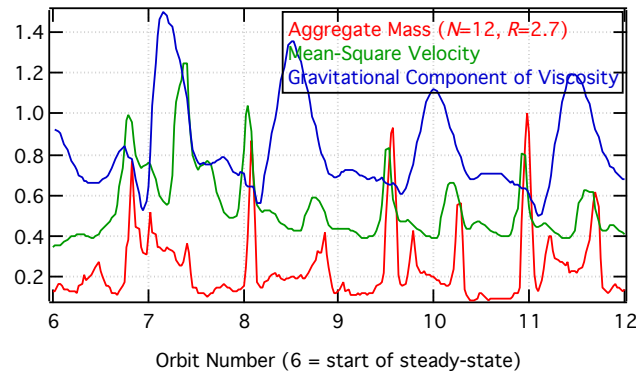
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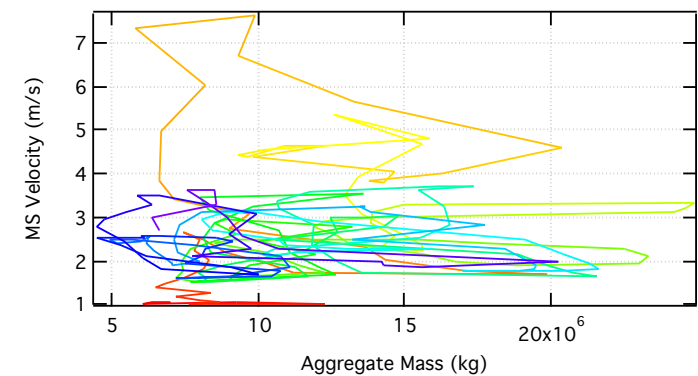
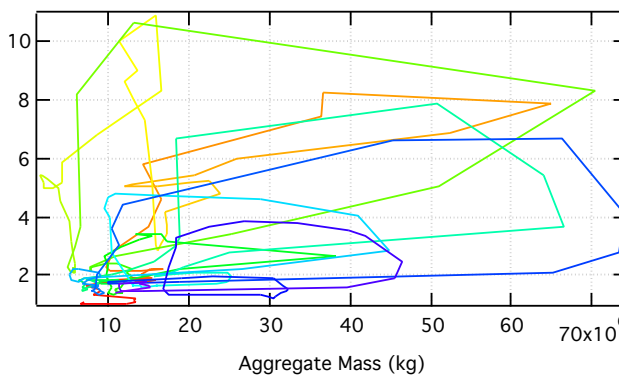
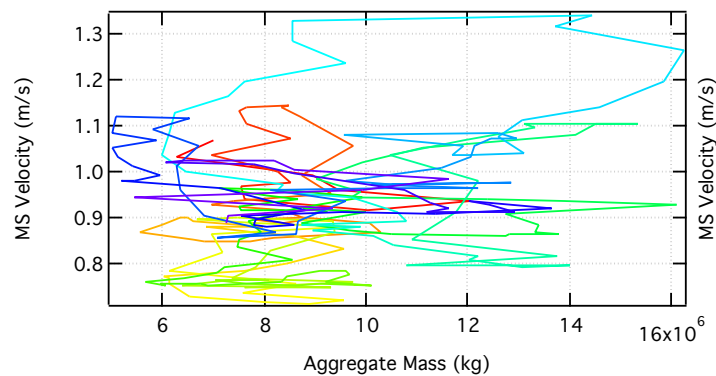
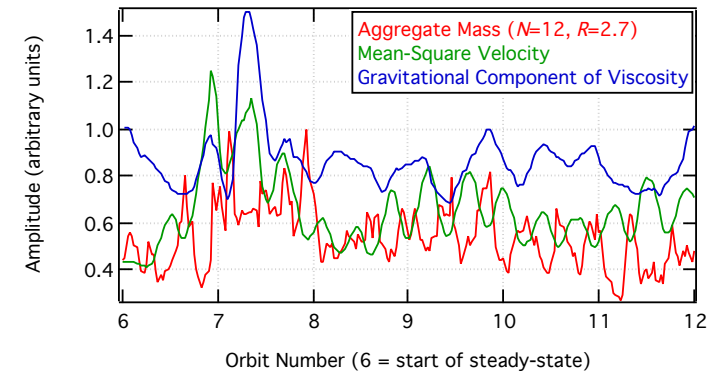
## Unforced



## Forced Slow, A Lot

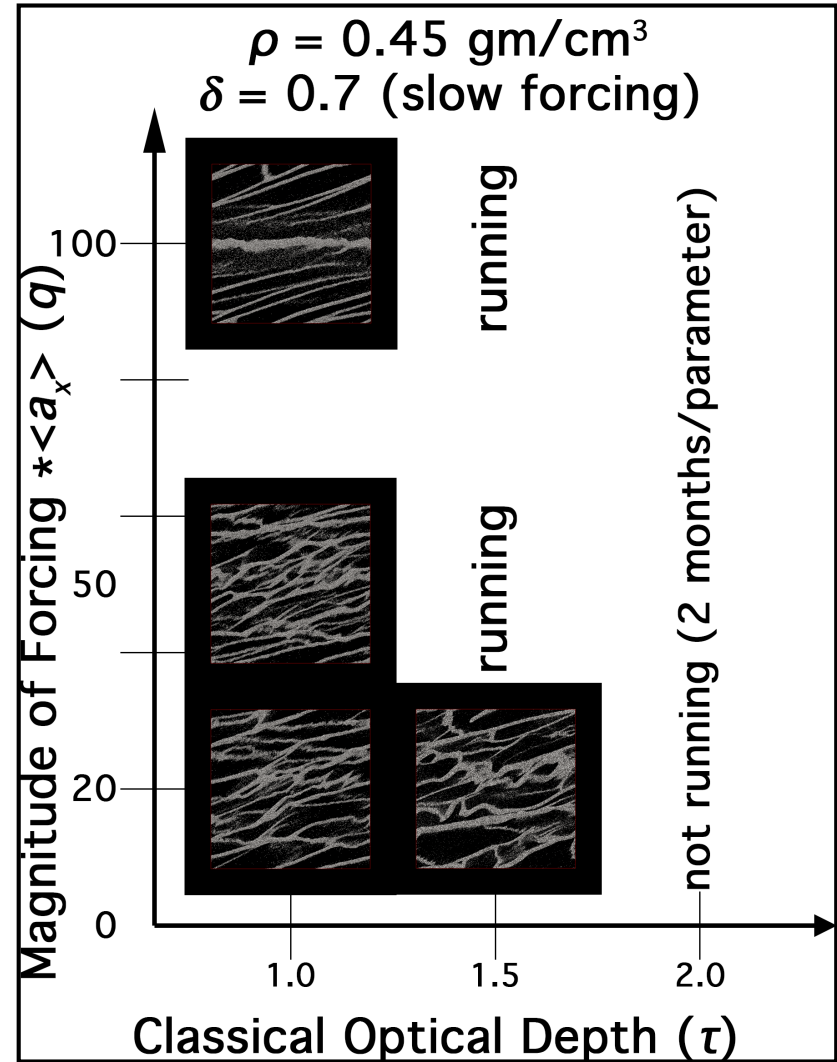
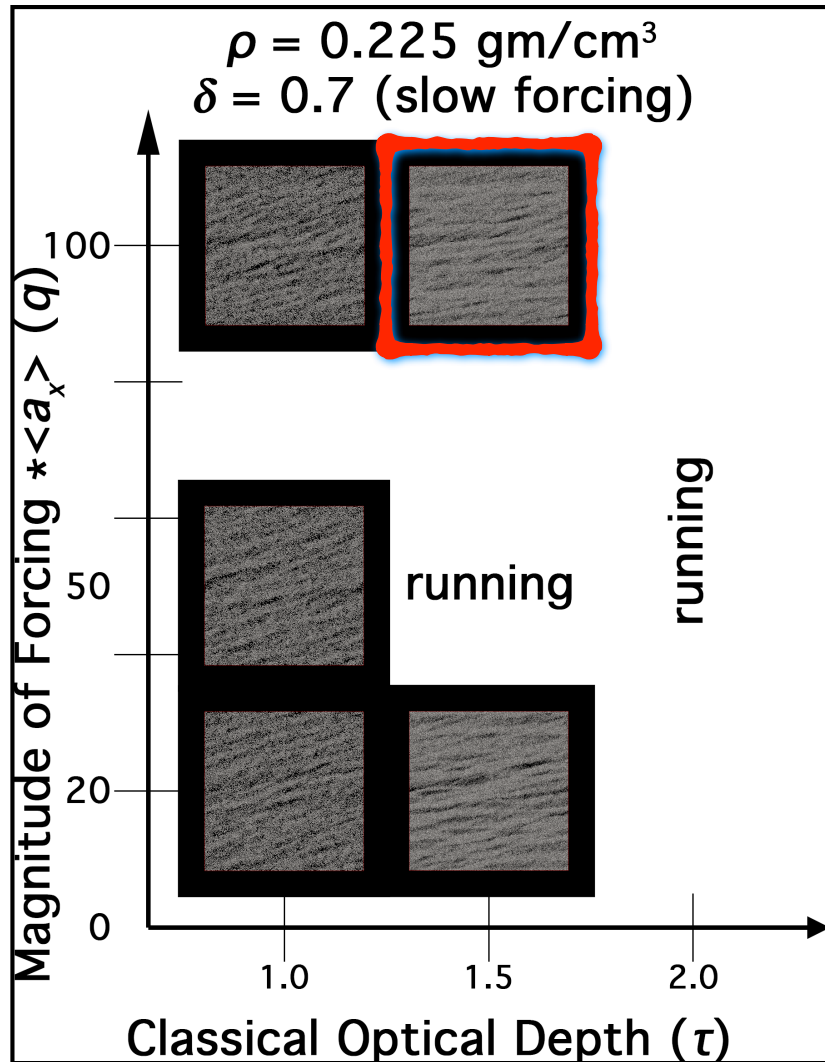


## Forced Fast, A Lot



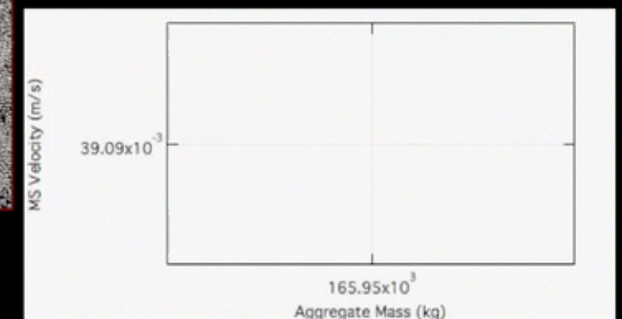
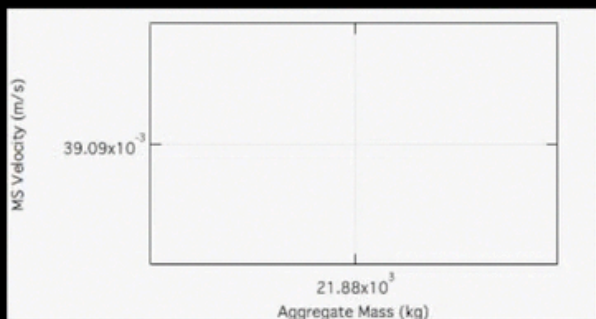
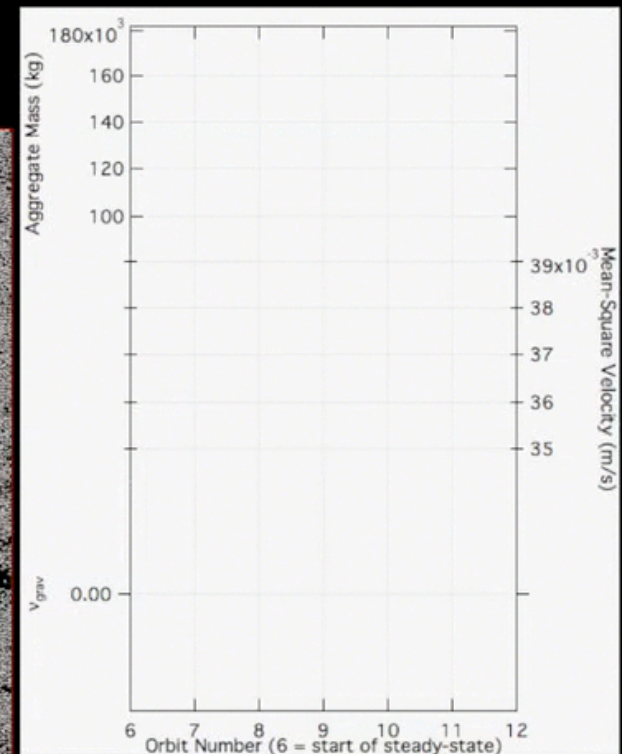
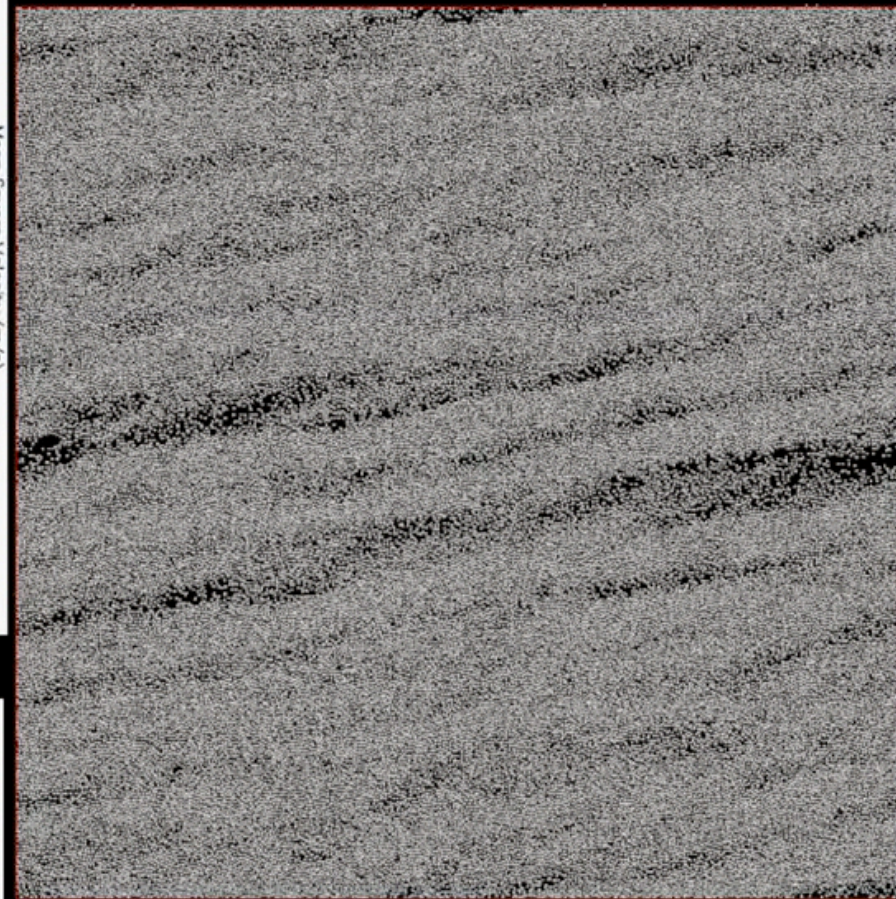
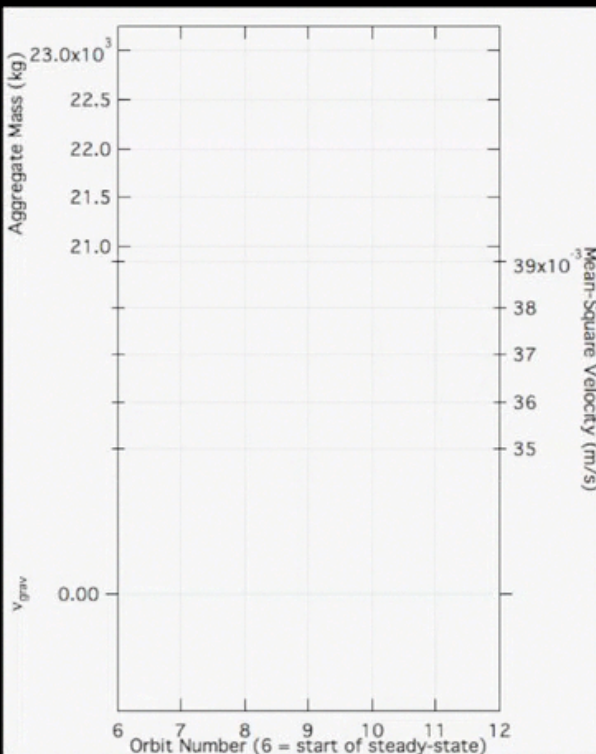
RESULTS:

# NAVIGATIONAL CHART



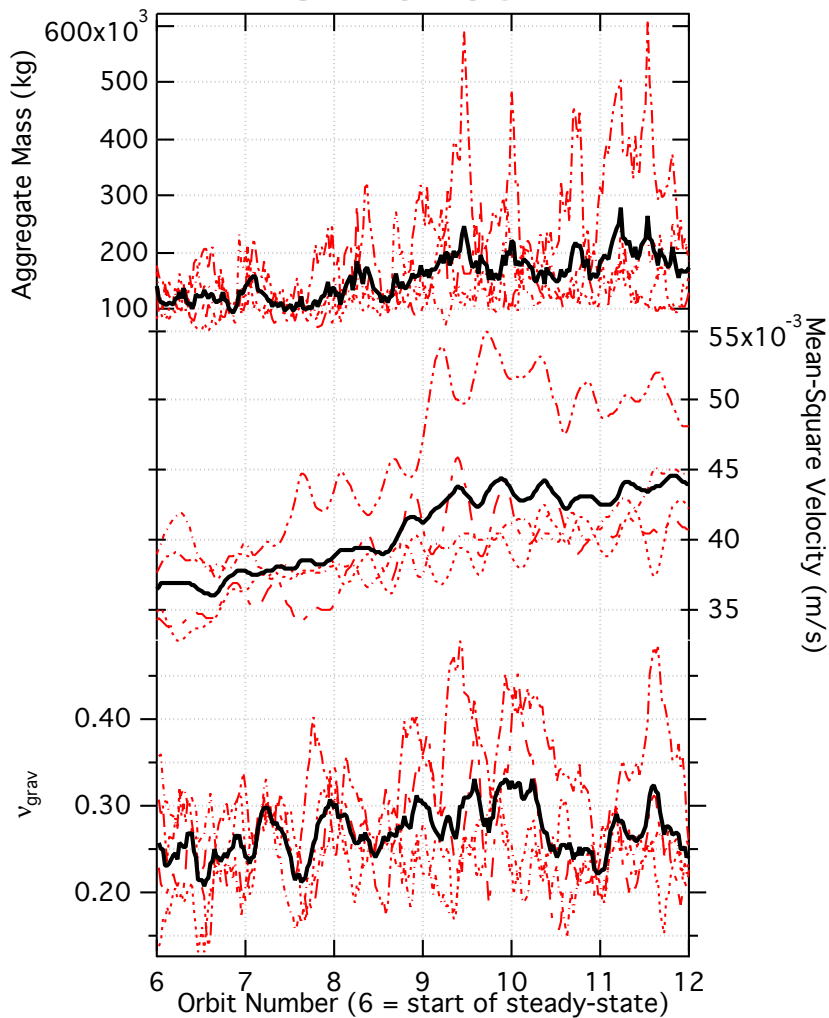
# RESULTS (VISCIOUS OVER-STABILITY?):

$$\tau = 1.5, \rho = 0.225, q = 100\times, \delta = 0.7$$

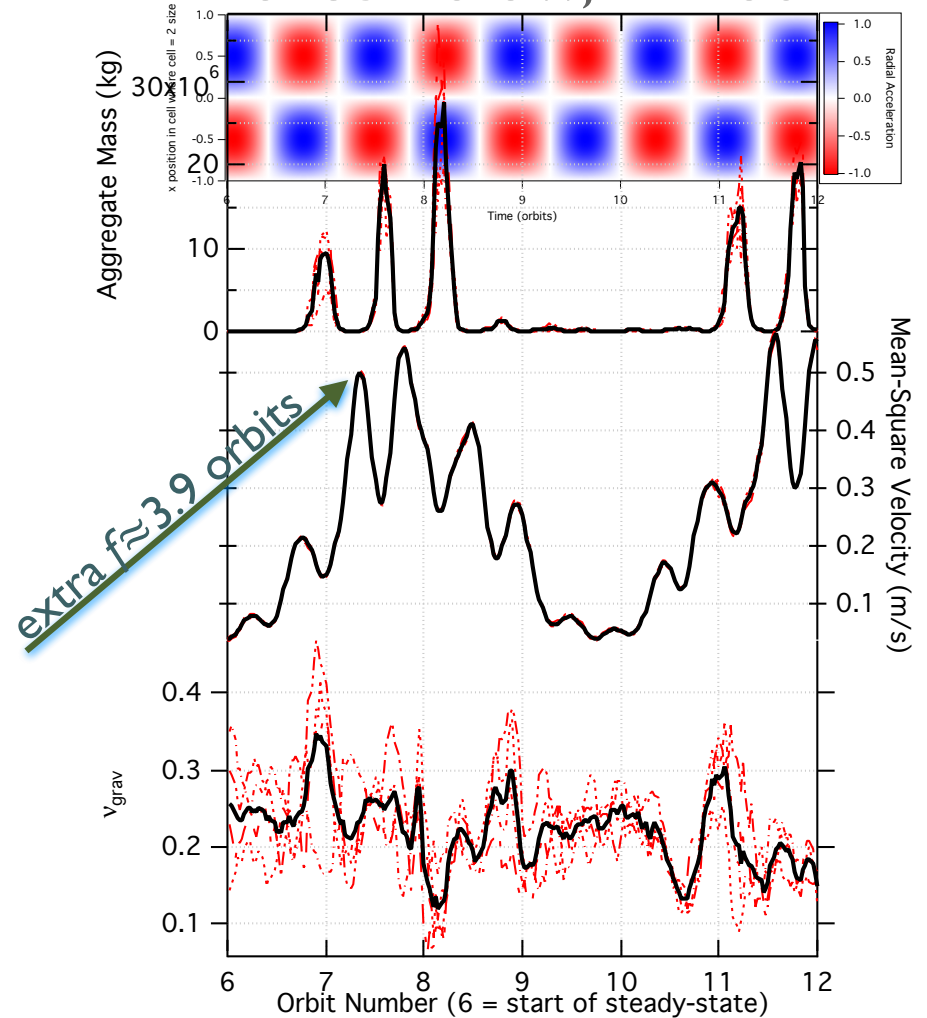


# RESULTS (CLUSTER CODE "CLUMPS" PARAMETERS): $\tau=1.5$ , $\rho=0.225$ , $q=100\times$ , $\delta=0.7$

## Unforced



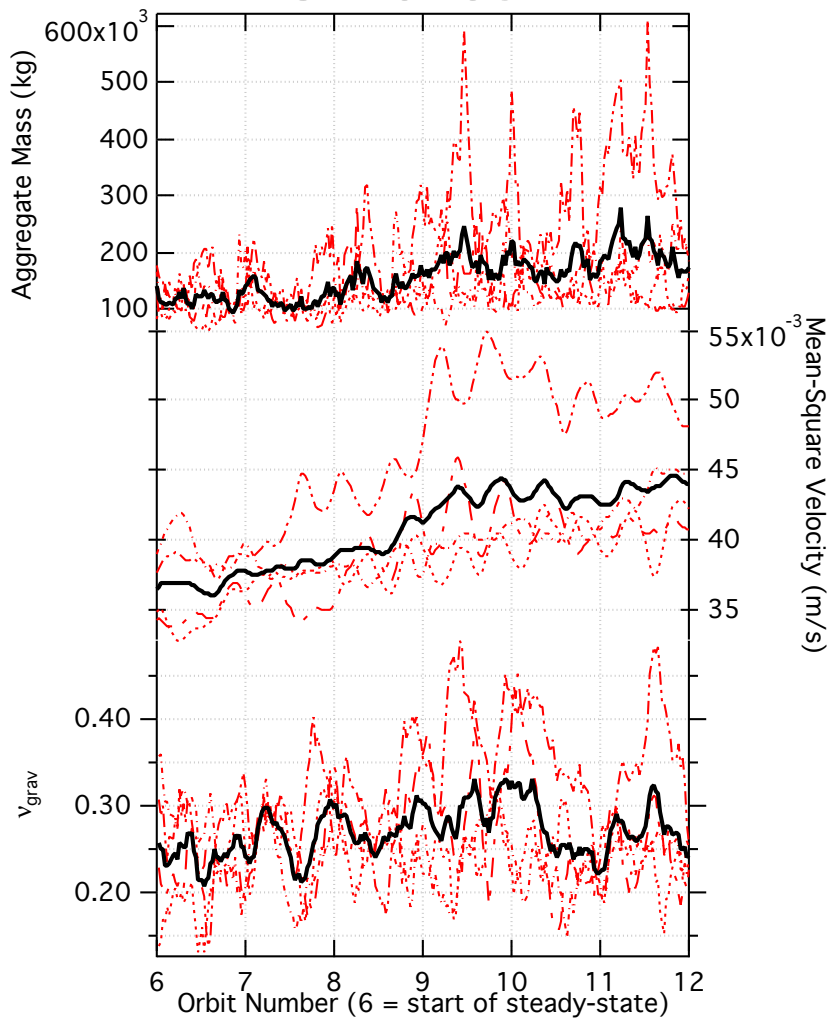
## Forced Slow, A Lot



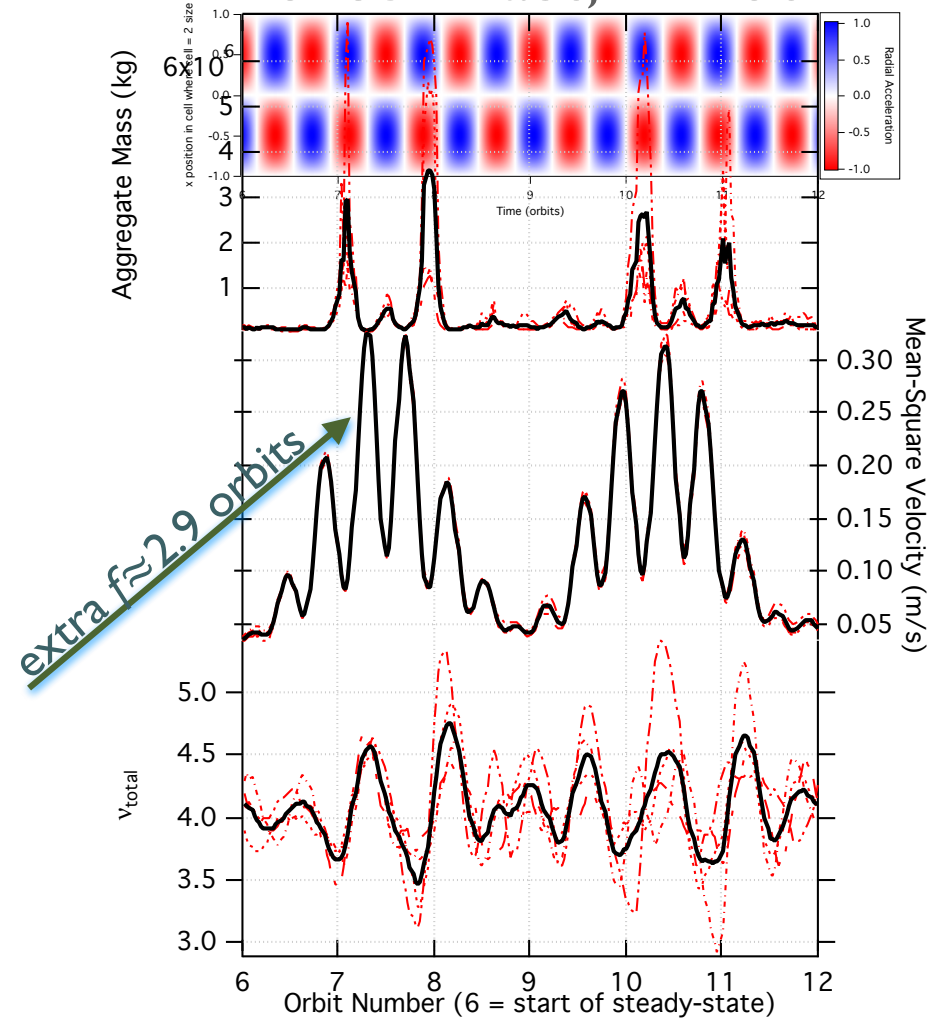
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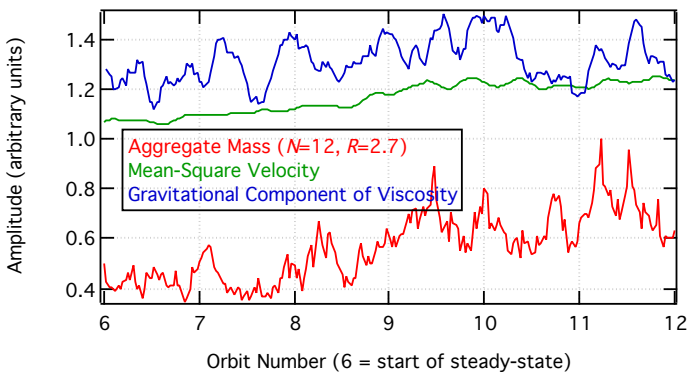
## Forced Fast, A Lot



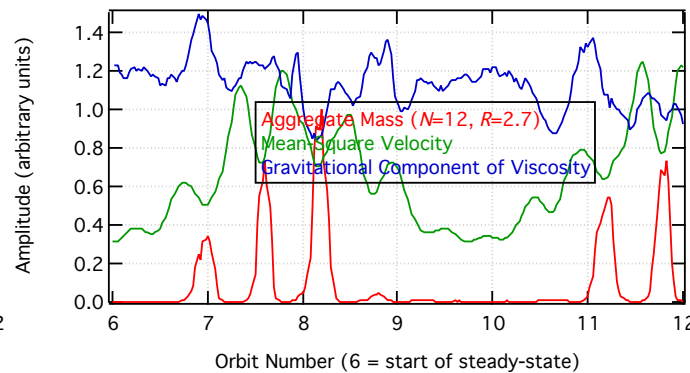
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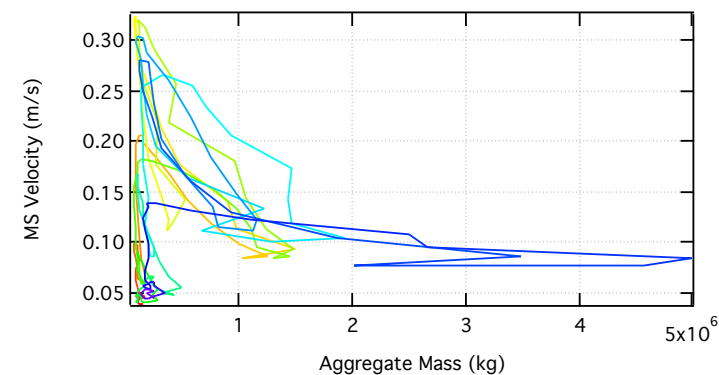
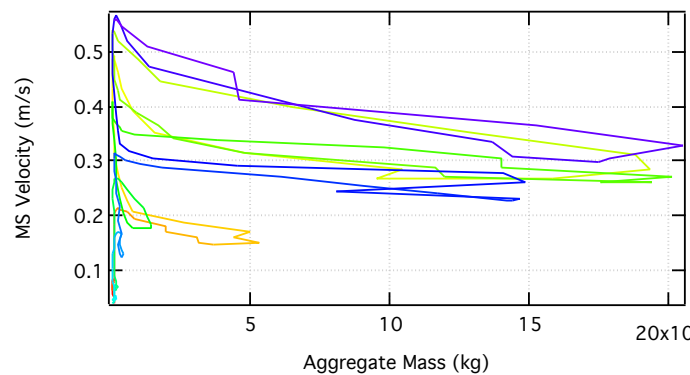
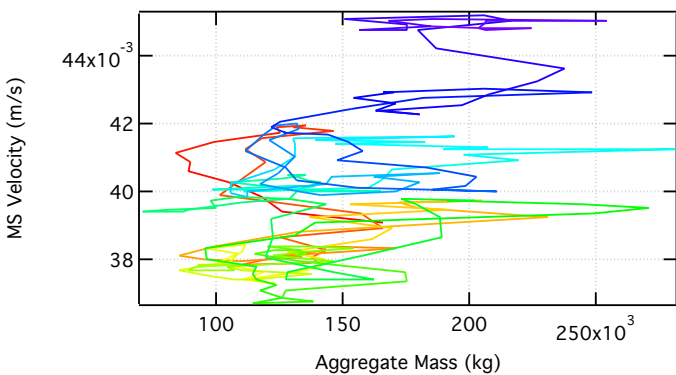
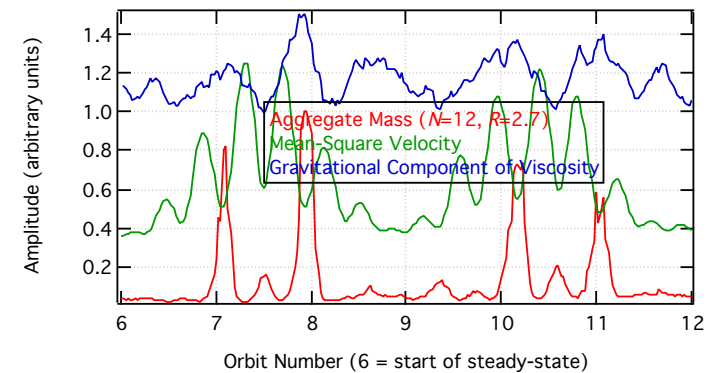
## Unforced



## Forced Slow, A Lot

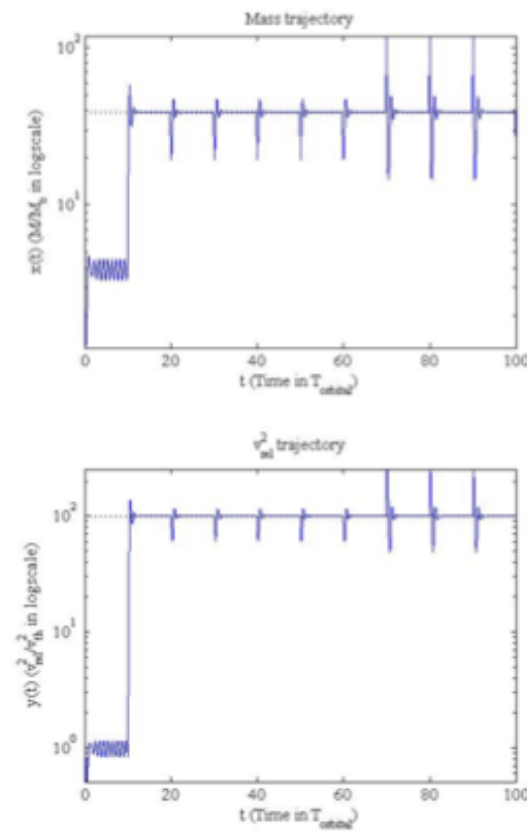
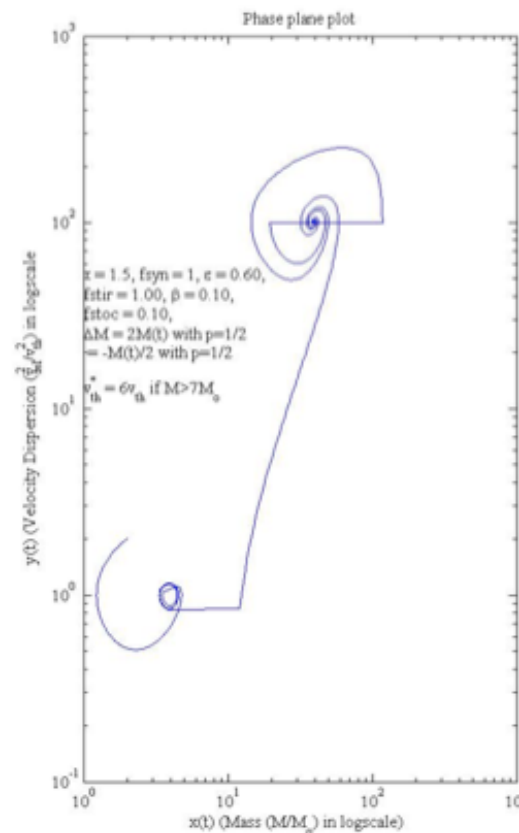


## Forced Fast, A Lot



# SUMMARY OF PROGRESS

- $N$ -body simulations to test predator-prey analytic model.
- Lots of simulations for large parameter space; several per parameter set.
- Several simulations do *not* show predator-prey characteristics (cycling in phase space and phase lags).
- But, some simulations do.



Gravity-dominated clumps give a new fixed point