

## Jovian Magnetic Field Models: VIP4, VIT4, VIPAL

### **VIP4:**

- First presented in Connerney et al. (1998)
- Fourth order
- Uses Connerney et al. (1981,1982) for the Jovian magnetodisc field
- Solved as a partial solution to a linearized system. See Connerney et al. (1981)
- Uses the following observations:
  - Io flux tube (IFT) footprint
    - Infrared images from the National Science Foundation camera (NSFCAM) at the Infrared Telescope Facility (IRTF)
    - Ultraviolet images with the Hubble Space Telescope (HST)
    - No distinction made between NSFCAM and HST observations because of good agreement between the two for latitude
    - Errors:  $\pm 1^\circ$  latitude and  $\pm 2^\circ$ - $15^\circ$  longitude
      - Poorer longitude errors from northern longitudes  $285^\circ$ - $355^\circ \lambda_{III}$
    - Northern longitudes  $0^\circ$ - $150^\circ \lambda_{III}$  sparsely sampled
    - 112 IFT footprints total
  - Pioneer 11
    - Vector Helium magnetometer 1-min averages
    - Scalar observations from  $<2.4 R_J$
    - Vector observations from  $2.4$ - $8.0 R_J$
    - Weighted by estimated accuracy of measurement
    - Field magnitude only from closest distances because of potential attitude uncertainties
  - Voyager 1
    - Fluxgate 48-s averages of vector field
    - $<10 R_J$
    - Weighted with constant magnitude errors

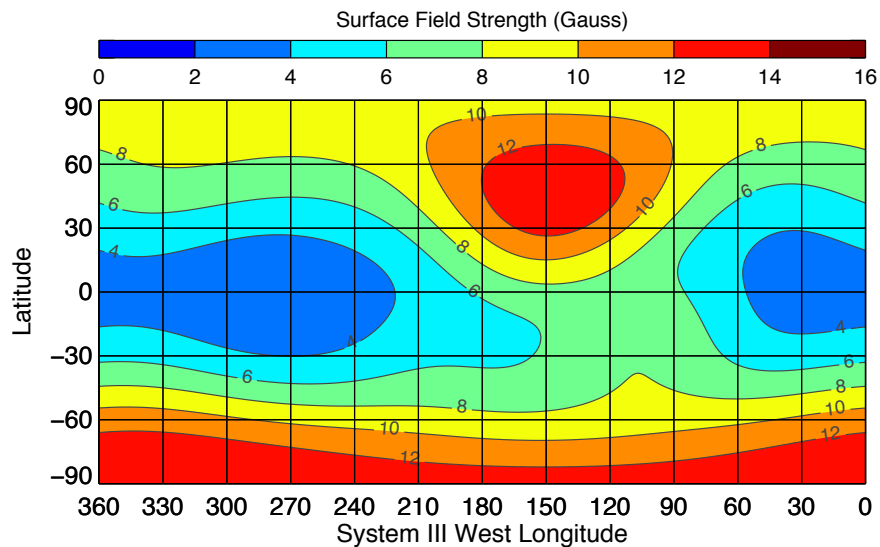
### **VIT4:**

- First presented in Connerney (2007)
- Fourth order
- Uses the same methodology as VIP4
- Uses IFT and a minimum of *in situ* data:
  - Over 500 IFT observations from Connerney et al. (1998)
  - Voyager 1 data least influenced by external fields
    - $\theta$ -component only
    - $<7 R_J$
    - Field strength limited between 1036-3280 nT

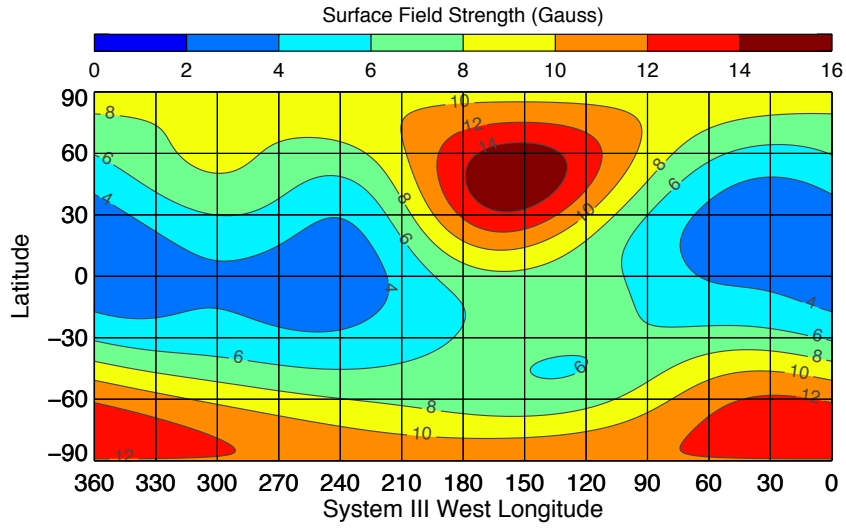
## **VIPAL:**

- First presented in Hess et al. (2011)
- Fifth order
- Began with the VIP4 model and systematically changed Schmidt Coefficients
  - Corrected the longitudinal position based on the location of Io plus a lead angle for Alfvén wave propagation
  - Corrected changes in latitude using a variations method that includes the fits mean error from Voyager 1 and Pioneer 10 and 11 data
  - Minimizes coefficients for uniqueness
- Uses the following observations:
  - IFT footprint
    - Ultraviolet images from the Space Telescope Imaging Spectrograph (STIS) and Advanced Camera for Surveys (ACS) on HST
  - Voyager 1 and Pioneer 10 and 11
    - Used to normalize coefficients and a few further constraints on free parameters
    - Subtracts current sheet magnetic field using Connerney (1981) model
    - $<10 R_J$

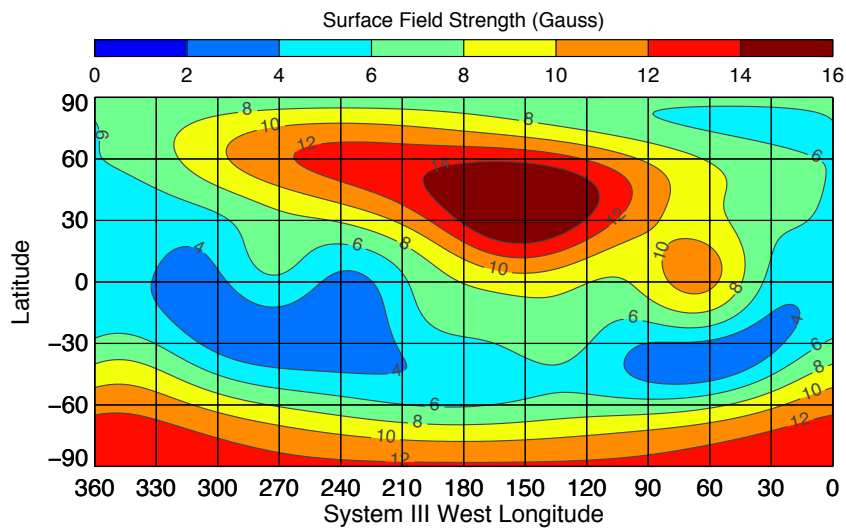
## **VIT4 Surface Field**



## VIP4 Surface Field

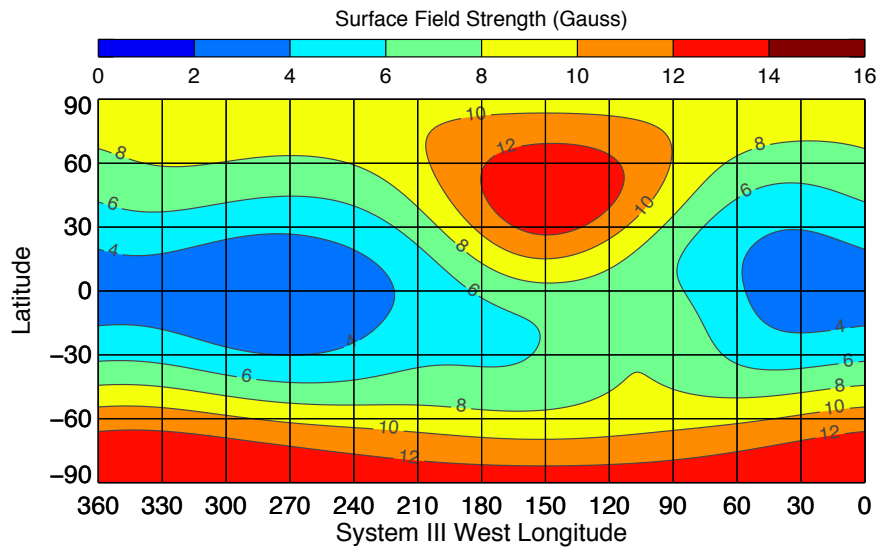


## VIPAL Surface Field

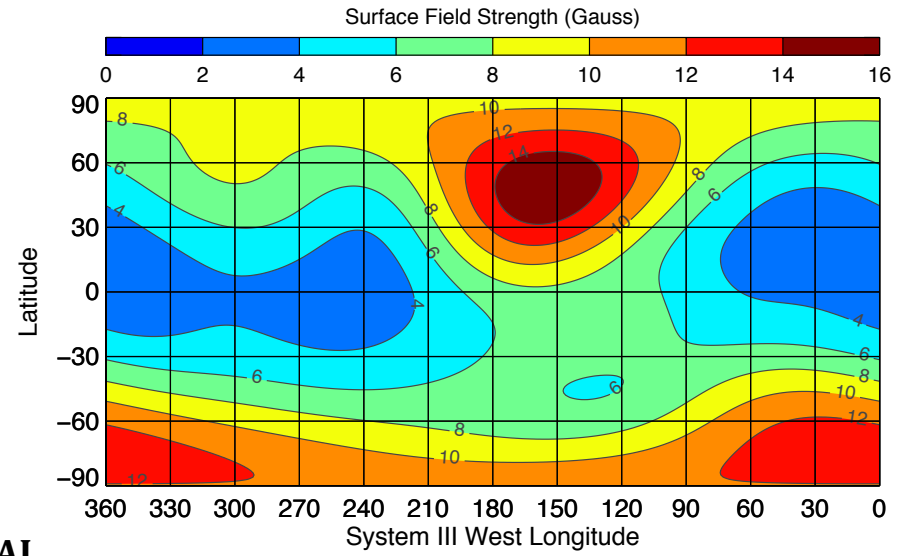


VIP4	VIT4	VIPAL
First in Connerney et al. (1998)	First presented in Connerney (2007)	First presented in Hess et al. (2011)
4 <sup>th</sup> Order	4 <sup>th</sup> Order	5 <sup>th</sup> Order
<p>Uses Connerney et al. (1981,1982) for the Jovian magnetodisc field. Solved as a partial solution to a linearized system-Connerney et al. (1981)</p> <p><b>Io flux tube (IFT) footprint</b></p> <ul style="list-style-type: none"> <li>▪ Infrared images from the NSFCAM at IRTF</li> <li>▪ Ultraviolet images with the HST</li> <li>▪ No distinction made between NSFCAM and HST observations because of good agreement between the two for latitude</li> <li>▪ Errors: <math>\pm 1^\circ</math> latitude and <math>\pm 2^\circ</math>-<math>15^\circ</math> longitude</li> <li>• Poorer longitude errors from northern longitudes <math>285^\circ</math>-<math>355^\circ \lambda_{III}</math></li> <li>▪ Northern longitudes <math>0^\circ</math>-<math>150^\circ \lambda_{III}</math> sparsely sampled</li> <li>▪ 112 IFT footprints total</li> </ul> <p><b>Pioneer 11</b></p> <ul style="list-style-type: none"> <li>▪ Vector Helium magnetometer 1-min averages</li> <li>▪ Scalar observations from <math>&lt;2.4 R_J</math></li> <li>▪ Vector observations from <math>2.4</math>-<math>8.0 R_J</math></li> <li>▪ Weighted by estimated accuracy of measurement</li> <li>▪ Field magnitude only from closest distances because of potential attitude uncertainties</li> </ul> <p><b>Voyager 1</b></p> <ul style="list-style-type: none"> <li>▪ Fluxgate 48-s averages of vector field</li> <li>▪ <math>&lt;10 R_J</math></li> <li>▪ Weighted with constant magnitude errors</li> </ul>	<p>Uses the same methodology as VIP4</p> <p><b>Uses IFT and a minimum of <i>in situ</i> data:</b></p> <ul style="list-style-type: none"> <li>• Over 500 IFT observations from Connerney et al. (1998)</li> </ul> <p><b>Voyager 1 data</b> least influenced by external fields</p> <ul style="list-style-type: none"> <li>▪ <math>\theta</math>-component only</li> <li>▪ <math>&lt;7 R_J</math></li> </ul> <p>Field strength limited between 1036-3280 nT</p>	<ul style="list-style-type: none"> <li>• Began with the VIP4 model and systematically changed Schmidt Coefficients</li> <li>• Corrected the longitudinal position based on the location of Io plus a lead angle for Alfvén wave propagation</li> <li>• Corrected changes in latitude using a variations method that includes the fits mean error from Voyager 1 and Pioneer 10 and 11 data</li> <li>• Minimizes coefficients for uniqueness</li> </ul> <p><b>IFT footprint</b></p> <ul style="list-style-type: none"> <li>• Ultraviolet images from STIS and ACS on HST</li> </ul> <p><b>Voyager 1 and Pioneer 10 and 11</b></p> <ul style="list-style-type: none"> <li>• Used to normalize coefficients and a few further constraints on free parameters</li> <li>• Subtracts current sheet magnetic field using Connerney (1981) model</li> <li>• <math>&lt;10 R_J</math></li> </ul>

### VIT4



### VIP4



### VIPAL

